# **A**P<sup>°</sup>

# AP<sup>®</sup> Physics 1: Algebra-Based 2016 Free-Response Questions

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CONSTANTS AND CONVERSION FACTORS					
Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude,	$e = 1.60 \times 10^{-19} \text{ C}$			
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant,	$k = 1/4\pi\varepsilon_0 = 9.0 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2$			
Electron mass, $m_e = 9.11 \times 10^{-31} \text{ kg}$	Universal gravitational constant,	$G = 6.67 \times 10^{-11} \text{ m}^3/\text{kg} \cdot \text{s}^2$			
Speed of light, $c = 3.00 \times 10^8 \text{ m/s}$	Acceleration due to gravity at Earth's surface,	$g = 9.8 \text{ m/s}^2$			

## **AP<sup>®</sup> PHYSICS 1 TABLE OF INFORMATION**

	meter,	m	kelvin,	Κ	watt,	W	degree Celsius,	°C
UNIT	kilogram,	kg	hertz,	Hz	coulomb,	С		
SYMBOLS	second,	S	newton,	Ν	volt,	V		
	ampere,	А	joule,	J	ohm,	Ω		

	PREFIXES					
Factor	Prefix	Symbol				
10 <sup>12</sup>	tera	Т				
10 <sup>9</sup>	giga	G				
10 <sup>6</sup>	mega	М				
10 <sup>3</sup>	kilo	k				
10 <sup>-2</sup>	centi	с				
10 <sup>-3</sup>	milli	m				
10 <sup>-6</sup>	micro	μ				
10 <sup>-9</sup>	nano	n				
10 <sup>-12</sup>	pico	р				

VALUES OF	VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES						
θ	$0^{\circ}$	$30^{\circ}$	$37^{\circ}$	$45^{\circ}$	$53^{\circ}$	$60^{\circ}$	$90^{\circ}$
sin $ heta$	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
tan θ	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	∞

The following conventions are used in this exam.

- I. The frame of reference of any problem is assumed to be inertial unless otherwise stated.
- II. Assume air resistance is negligible unless otherwise stated.
- III. In all situations, positive work is defined as work done <u>on</u> a system.
- IV. The direction of current is conventional current: the direction in which positive charge would drift.
- V. Assume all batteries and meters are ideal unless otherwise stated.

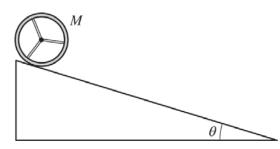
## **AP<sup>®</sup> PHYSICS 1 EQUATIONS**

MEC	HANICS	ELECTRICITY		
$v_x = v_{x0} + a_x t$ $x = x_0 + v_{x0}t + \frac{1}{2}a_x t^2$ $v_x^2 = v_{x0}^2 + 2a_x (x - x_0)$ $\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$ $ \vec{F}_f  \le \mu  \vec{F}_n $ $a_c = \frac{v^2}{r}$ $\vec{p} = m\vec{v}$	$a = \operatorname{acceleration} A$ $A = \operatorname{amplitude} d$ $d = \operatorname{distance} B$ $E = \operatorname{energy} f$ $f = \operatorname{frequency} F$ $F = \operatorname{force} B$ $I = \operatorname{rotational inertia} B$ $K = \operatorname{kinetic energy} B$ $k = \operatorname{spring constant} B$ $L = \operatorname{angular momentum} B$ $\ell = \operatorname{length} B$ $m = \operatorname{mass} B$ $P = \operatorname{power} B$ $p = \operatorname{momentum} B$ $r = \operatorname{radius or separation} B$	$\begin{aligned} \left  \vec{F}_E \right  &= k \left  \frac{q_1 q_2}{r^2} \right  \\ I &= \frac{\Delta q}{\Delta t} \\ R &= \frac{\rho \ell}{A} \\ I &= \frac{\Delta V}{R} \\ P &= I \Delta V \\ R_s &= \sum_i R_i \\ \frac{1}{R_p} &= \sum_i \frac{1}{R_i} \end{aligned}$	A = area F = force I = current $\ell = \text{length}$ P = power q = charge R = resistance r = separation t = time V = electric potential $\rho = \text{resistivity}$	
$\Delta \vec{p} = \vec{F} \Delta t$ $K = \frac{1}{2} m v^2$	T = period t = time U = potential energy V = volume v = speed	$\lambda = \frac{v}{f} \qquad f = v = v$	AVES frequency speed wavelength	
$\Delta E = W = F_{\parallel}d = Fd\cos\theta$ $P = \frac{\Delta E}{\Delta t}$ $\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$	W =  work done on a system x = position y = height $\alpha = \text{angular acceleration}$ $\mu = \text{coefficient of friction}$ $\theta = \text{angle}$	Rectangle A = bh Triangle	<b>D TRIGONOMETRY</b> A = area C = circumference V = volume S = surface area	
$\omega = \omega_0 + \alpha t$ $x = A\cos(2\pi ft)$ $\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$	$\rho$ = density $\tau$ = torque $\omega$ = angular speed $\Delta U_g$ = $mg \Delta y$	$A = \frac{1}{2}bh$ Circle $A = \pi r^{2}$ $C = 2\pi r$	$b = base$ $h = height$ $\ell = length$ $w = width$ $r = radius$	
$\begin{aligned} u &= \frac{1}{I} = \frac{1}{I} \\ \tau &= r_{\perp}F = rF\sin\theta \\ L &= I\omega \end{aligned}$	$T = \frac{2\pi}{\omega} = \frac{1}{f}$ $T_s = 2\pi \sqrt{\frac{m}{k}}$	Rectangular solid $V = \ell w h$ Cylinder	Right triangle $c^2 = a^2 + b^2$ $\sin\theta = \frac{a}{c}$	
$\Delta L = \tau \Delta t$ $K = \frac{1}{2}I\omega^2$	$T_p = 2\pi \sqrt{\frac{\ell}{g}}$	$V = \pi r^{2} \ell$ $S = 2\pi r \ell + 2\pi r^{2}$ Sphere	$\cos\theta = \frac{b}{c}$ $\tan\theta = \frac{a}{b}$	
$\left \vec{F}_{s}\right  = k\left \vec{x}\right $ $U_{s} = \frac{1}{2}kx^{2}$	$\begin{vmatrix} \vec{F}_g \end{vmatrix} = G \frac{m_1 m_2}{r^2}$ $\vec{g} = \frac{\vec{F}_g}{m}$	$V = \frac{4}{3}\pi r^3$ $S = 4\pi r^2$	c $\theta$ 90° b $a$	
$\rho = \frac{m}{V}$	$U_G = -\frac{Gm_1m_2}{r}$			

#### PHYSICS 1

#### Section II 5 Questions Time—90 minutes

**Directions:** Questions 1, 4 and 5 are short free-response questions that require about 13 minutes each to answer and are worth 7 points each. Questions 2 and 3 are long free-response questions that require about 25 minutes each to answer and are worth 12 points each. Show your work for each part in the space provided after that part.

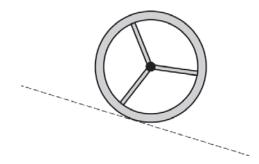


1. (7 points, suggested time 13 minutes)

A wooden wheel of mass M, consisting of a rim with spokes, rolls down a ramp that makes an angle  $\theta$  with the horizontal, as shown above. The ramp exerts a force of static friction on the wheel so that the wheel rolls without slipping.

(a)

i. On the diagram below, draw and label the forces (not components) that act on the wheel as it rolls down the ramp, which is indicated by the dashed line. To clearly indicate at which point on the wheel each force is exerted, draw each force as a distinct arrow starting on, and pointing away from, the point at which the force is exerted. The lengths of the arrows need not indicate the relative magnitudes of the forces.



ii. As the wheel rolls down the ramp, which force causes a change in the angular velocity of the wheel with respect to its center of mass?

Briefly explain your reasoning.

(b) For this ramp angle, the force of friction exerted on the wheel is less than the maximum possible static friction force. Instead, the magnitude of the force of static friction exerted on the wheel is 40 percent of the magnitude of the force or force component directed opposite to the force of friction. Derive an expression for the linear acceleration of the wheel's center of mass in terms of M,  $\theta$ , and physical constants, as appropriate.

- (c) In a second experiment on the same ramp, a block of ice, also with mass M, is released from rest at the same instant the wheel is released from rest, and from the same height. The block slides down the ramp with negligible friction.
  - i. Which object, if either, reaches the bottom of the ramp with the greatest speed?

\_\_\_\_\_Wheel \_\_\_\_\_Block \_\_\_\_\_Neither; both reach the bottom with the same speed.

Briefly explain your answer, reasoning in terms of forces.

ii. Briefly explain your answer again, now reasoning in terms of energy.

2. (12 points, suggested time 25 minutes)

A new kind of toy ball is advertised to "bounce perfectly elastically" off hard surfaces. A student suspects, however, that no collision can be perfectly elastic. The student hypothesizes that the collisions are very close to being perfectly elastic for low-speed collisions but that they deviate more and more from being perfectly elastic as the collision speed increases.

- (a) Design an experiment to test the student's hypothesis about collisions of the ball with a hard surface. The student has equipment that would usually be found in a school physics laboratory.
  - i. What quantities would be measured?
  - ii. What equipment would be used for the measurements, and how would that equipment be used?
  - iii. Describe the procedure to be used to test the student's hypothesis. Give enough detail so that another student could replicate the experiment.
- (b) Describe how you would represent the data in a graph or table. Explain how that representation would be used to determine whether the data are consistent with the student's hypothesis.
- (c) A student carries out the experiment and analysis described in parts (a) and (b). The student immediately concludes that something went wrong in the experiment because the graph or table shows behavior that is elastic for low-speed collisions but appears to violate a basic physics principle for high-speed collisions.
  - i. Give an example of a graph or table that indicates nearly elastic behavior for low-speed collisions but appears to violate a basic physics principle for high-speed collisions.
  - ii. State one physics principle that appears to be violated in the graph or table given in part (c)i. Several physics principles might appear to be violated, but you only need to identify one.

Briefly explain what aspect of the graph or table indicates that the physics principle is violated, and why.

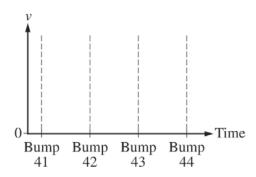
M		
		θ

Note: Figure not drawn to scale.

3. (12 points, suggested time 25 minutes)

A long track, inclined at an angle  $\theta$  to the horizontal, has small speed bumps on it. The bumps are evenly spaced a distance *d* apart, as shown in the figure above. The track is actually much longer than shown, with over 100 bumps. A cart of mass *M* is released from rest at the top of the track. A student notices that after reaching the 40th bump the cart's average speed between successive bumps no longer increases, reaching a maximum value  $v_{avg}$ . This means the time interval taken to move from one bump to the next bump becomes constant.

- (a) Consider the cart's motion between bump 41 and bump 44.
  - i. In the figure below, sketch a graph of the cart's velocity v as a function of time from the moment it reaches bump 41 until the moment it reaches bump 44.
  - ii. Over the same time interval, draw a dashed horizontal line at  $v = v_{avg}$ . Label this line " $v_{avg}$ ".



(b) Suppose the distance between the bumps is increased but everything else stays the same.

Is the maximum speed of the cart now greater than, less than, or the same as it was with the bumps closer together?

\_\_\_\_ Greater than \_\_\_\_ Less than \_\_\_\_ The same as

Briefly explain your reasoning.

(c) With the bumps returned to the original spacing, the track is tilted to a greater ramp angle  $\theta$ . Is the maximum speed of the cart greater than, less than, or the same as it was when the ramp angle was smaller?

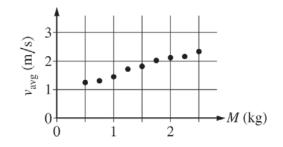
\_\_\_\_ Greater than \_\_\_\_ Less than \_\_\_\_ The same as

Briefly explain your reasoning.

(d) Before deriving an equation for a quantity such as  $v_{avg}$ , it can be useful to come up with an equation that is intuitively expected to be true. That way, the derivation can be checked later to see if it makes sense physically. A student comes up with the following equation for the cart's maximum average speed:  $\sigma Mg\sin\theta$ 

 $v_{\text{avg}} = C \frac{Mg \sin \theta}{d}$ , where *C* is a positive constant.

i. To test the equation, the student rolls a cart down the long track with speed bumps many times in front of a motion detector. The student varies the mass M of the cart with each trial but keeps everything else the same. The graph shown below is the student's plot of the data for  $v_{avg}$  as a function of M.



Are these data consistent with the student's equation?

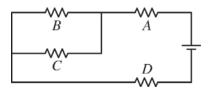
\_\_\_\_Yes \_\_\_\_No

Briefly explain your reasoning.

ii. Another student suggests that whether or not the data above are consistent with the equation, the equation could be incorrect for other reasons. Does the equation make physical sense?

\_\_\_\_Yes \_\_\_\_No

Briefly explain your reasoning.



4. (7 points, suggested time 13 minutes)

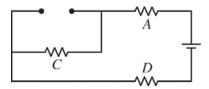
A circuit contains a battery and four identical resistors arranged as shown in the diagram above.

(a) Rank the magnitude of the potential difference across each resistor from greatest to least. If any resistors have potential differences with the same magnitude, state that explicitly. Briefly explain your reasoning.

Ranking:

Brief explanation:

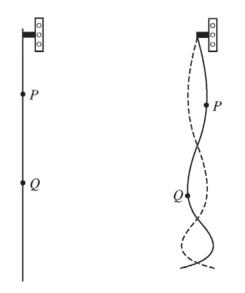
Resistor *B* is now removed from the circuit, and there is no connection between the wires that were attached to it. The new circuit diagram is shown below.



(b) When resistor *B* is removed, does the current through resistor *A* increase, decrease, or remain the same? \_\_\_\_\_ Increase \_\_\_\_\_ Decrease \_\_\_\_\_ Remain the same

Briefly explain your reasoning.

(c) When resistor *B* is removed, does the current through resistor *C* increase, decrease, or remain the same?
 \_\_\_\_\_ Increase \_\_\_\_\_ Decrease \_\_\_\_\_ Remain the same
 Briefly explain your reasoning.



5. (7 points, suggested time 13 minutes)

The figure above on the left shows a uniformly thick rope hanging vertically from an oscillator that is turned off. When the oscillator is on and set at a certain frequency, the rope forms the standing wave shown above on the right. P and Q are two points on the rope.

- (a) The tension at point P is greater than the tension at point Q. Briefly explain why.
- (b) A student hypothesizes that increasing the tension in a rope increases the speed at which waves travel along the rope. In a clear, coherent paragraph-length response that may also contain figures and/or equations, explain why the standing wave shown above supports the student's hypothesis.

#### STOP

#### END OF EXAM

2017



# AP Physics 1: Algebra-Based

# **Free-Response Questions**

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Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant,	$k = 1/4\pi\varepsilon_0 = 9.0 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2$			
Electron mass, $m_e = 9.11 \times 10^{-31} \text{ kg}$	Universal gravitational constant,	$G = 6.67 \times 10^{-11} \text{ m}^3/\text{kg}\cdot\text{s}^2$			
Speed of light, $c = 3.00 \times 10^8 \text{ m/s}$	Acceleration due to gravity at Earth's surface,	$g = 9.8 \text{ m/s}^2$			

### **AP<sup>®</sup> PHYSICS 1 TABLE OF INFORMATION**

	meter,	m	kelvin,	Κ	watt,	W	degree Celsius,	°C
UNIT	kilogram,	kg	hertz,	Hz	coulomb,	С		
SYMBOLS	second,	S	newton,	Ν	volt,	V		
	ampere,	А	joule,	J	ohm,	Ω		

	PREFIXES					
Factor	Prefix	Symbol				
10 <sup>12</sup>	tera	Т				
10 <sup>9</sup>	giga	G				
10 <sup>6</sup>	mega	М				
10 <sup>3</sup>	kilo	k				
10 <sup>-2</sup>	centi	С				
$10^{-3}$	milli	m				
10 <sup>-6</sup>	micro	μ				
10 <sup>-9</sup>	nano	n				
10 <sup>-12</sup>	pico	р				

VALUES OF	VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES						
θ	$0^{\circ}$	$30^{\circ}$	$37^{\circ}$	$45^{\circ}$	$53^{\circ}$	$60^{\circ}$	$90^{\circ}$
sin $ heta$	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
$\tan \theta$	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	∞

The following conventions are used in this exam.

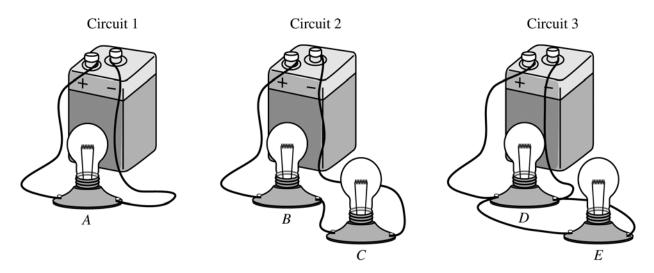
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- II. Assume air resistance is negligible unless otherwise stated.
- III. In all situations, positive work is defined as work done <u>on</u> a system.
- IV. The direction of current is conventional current: the direction in which positive charge would drift.
- V. Assume all batteries and meters are ideal unless otherwise stated.

# **AP<sup>®</sup> PHYSICS 1 EQUATIONS**

MEC	HANICS	ELECTRICITY		
$v_x = v_{x0} + a_x t$ $x = x_0 + v_{x0}t + \frac{1}{2}a_x t^2$ $v_x^2 = v_{x0}^2 + 2a_x (x - x_0)$ $\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$ $ \vec{F}_f  \le \mu  \vec{F}_n $ $a_c = \frac{v^2}{r}$ $\vec{p} = m\vec{v}$	$a = \operatorname{acceleration} A$ $A = \operatorname{amplitude} A$ $d = \operatorname{distance} B$ $E = \operatorname{energy} f$ $f = \operatorname{frequency} F$ $F = \operatorname{force} B$ $I = \operatorname{rotational inertia} B$ $K = \operatorname{kinetic energy} B$ $k = \operatorname{spring constant} B$ $L = \operatorname{angular momentum} B$ $\ell = \operatorname{length} B$ $m = \operatorname{mass} B$ $P = \operatorname{power} B$ $p = \operatorname{momentum} B$ $r = \operatorname{radius or separation} B$	$\begin{aligned} \left  \vec{F}_E \right  &= k \left  \frac{q_1 q_2}{r^2} \right  \\ I &= \frac{\Delta q}{\Delta t} \\ R &= \frac{\rho \ell}{A} \\ I &= \frac{\Delta V}{R} \\ P &= I \Delta V \\ R_s &= \sum_i R_i \\ \frac{1}{R_p} &= \sum_i \frac{1}{R_i} \end{aligned}$	A = area F = force I = current $\ell = \text{length}$ P = power q = charge R = resistance r = separation t = time V = electric potential $\rho = \text{resistivity}$	
$\Delta \vec{p} = \vec{F} \Delta t$ $K = \frac{1}{2} m v^2$	T = period t = time U = potential energy V = volume v = speed	$\lambda = \frac{v}{f} \qquad f = v$	AVES frequency speed wavelength	
$\Delta E = W = F_{\parallel}d = Fd\cos\theta$ $P = \frac{\Delta E}{\Delta t}$	W =  work done on a system x = position y = height $\alpha = \text{angular acceleration}$ $\mu = \text{coefficient of friction}$	<b>GEOMETRY ANI</b> Rectangle A = bh	<b>D TRIGONOMETRY</b> A = area C = circumference V = volume	
$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$ $\omega = \omega_0 + \alpha t$ $x = A\cos(2\pi ft)$	$\theta$ = angle $\rho$ = density $\tau$ = torque $\omega$ = angular speed	Triangle $A = \frac{1}{2}bh$ Circle	S = surface area b = base h = height $\ell = $ length w = width	
$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$ $\tau = r_{\perp}F = rF\sin\theta$	$\Delta U_g = mg \Delta y$ $T = \frac{2\pi}{\omega} = \frac{1}{f}$	$A = \pi r^{2}$ $C = 2\pi r$ Rectangular solid $V = \ell wh$	r = radius Right triangle $c^2 = a^2 + b^2$	
$L = I\omega$ $\Delta L = \tau \Delta t$ $K = \frac{1}{2}I\omega^{2}$	$T_s = 2\pi \sqrt{\frac{m}{k}}$ $T_p = 2\pi \sqrt{\frac{\ell}{g}}$	Cylinder $V = \pi r^2 \ell$ $S = 2\pi r \ell + 2\pi r^2$	$\sin\theta = \frac{a}{c}$ $\cos\theta = \frac{b}{c}$ $\tan\theta = \frac{a}{b}$	
$\left \vec{F}_{s}\right  = k\left \vec{x}\right $ $U_{s} = \frac{1}{2}kx^{2}$	$\left \vec{F}_{g}\right  = G \frac{m_{1}m_{2}}{r^{2}}$ $\vec{g} = \frac{\vec{F}_{g}}{m}$	Sphere $V = \frac{4}{3}\pi r^{3}$ $S = 4\pi r^{2}$	$\frac{c}{b} = \frac{b}{b}$	
$ \rho = \frac{m}{V} $	$U_G = -\frac{Gm_1m_2}{r}$			

#### PHYSICS 1 Section II 5 Questions Time—90 minutes

**Directions:** Questions 1, 4, and 5 are short free-response questions that require about 13 minutes each to answer and are worth 7 points each. Questions 2 and 3 are long free-response questions that require about 25 minutes each to answer and are worth 12 points each. Show your work for each part in the space provided after that part.



1. (7 points, suggested time 13 minutes)

In the three circuits shown above, the batteries are all identical, and the lightbulbs are all identical. In circuit 1 a single lightbulb is connected to the battery. In circuits 2 and 3, two lightbulbs are connected to the battery in different ways, as shown. The lightbulbs are labeled A-E.

(a) Rank the magnitudes of the potential differences across lightbulbs *A*, *B*, *C*, *D*, and *E* from largest to smallest. If any lightbulbs have the same potential difference across them, state that explicitly.

Ranking:

Briefly explain how you determined your ranking.

(b) The batteries all start with an identical amount of usable energy and are all connected to the lightbulbs in the circuits at the same time.

In which circuit will the battery run out of usable energy first?

\_\_\_\_ Circuit 1 \_\_\_\_ Circuit 2 \_\_\_\_ Circuit 3

In which circuit will the battery run out of usable energy last?

\_\_\_\_ Circuit 1 \_\_\_\_ Circuit 2 \_\_\_\_ Circuit 3

In a clear, coherent paragraph-length response that may also contain equations and drawings, explain your reasoning.

2. (12 points, suggested time 25 minutes)

A student wants to determine the coefficient of static friction between a long, flat wood board and a small wood block.

- (a) Describe an experiment for determining the coefficient of static friction between the wood board and the wood block. Assume equipment usually found in a school physics laboratory is available.
  - i. Draw a diagram of the experimental setup of the board and block. In your diagram, indicate each quantity that would be measured and draw or state what equipment would be used to measure each quantity.
  - ii. Describe the overall procedure to be used, including any steps necessary to reduce experimental uncertainty. Give enough detail so that another student could replicate the experiment.
- (b) Derive an equation for the coefficient of static friction in terms of quantities measured in the procedure from part (a).

A physics class consisting of six lab groups wants to test the hypothesis that the coefficient of static friction between the board and the block equals the coefficient of kinetic friction between the board and the block. Each group determines the coefficients of kinetic and static friction between the board and the block. The groups' results are shown below, with the class averages indicated in the bottom row.

Lab Group Number	Coefficient of Kinetic Friction	Coefficient of Static Friction
1	0.45	0.54
2	0.46	0.52
3	0.42	0.56
4	0.43	0.55
5	0.74	0.23
6	0.44	0.54
Average	0.49	0.49

(c) Based on these data, what conclusion should the students make about the hypothesis that the coefficients of static and kinetic friction are equal?

\_\_\_\_ The static and kinetic coefficients are equal.

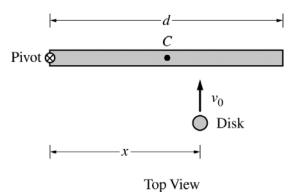
\_\_\_\_ The static and kinetic coefficients are not equal.

Briefly justify your reasoning.

(d) A metal disk is glued to the top of the wood block. The mass of the block-disk system is twice the mass of the original block. Does the coefficient of static friction between the bottom of the block and the board increase, decrease, or remain the same when the disk is added to the block?

\_\_\_\_Increase \_\_\_\_\_Remain the same

Briefly state your reasoning.



3. (12 points, suggested time 25 minutes)

The left end of a rod of length *d* and rotational inertia *I* is attached to a frictionless horizontal surface by a frictionless pivot, as shown above. Point *C* marks the center (midpoint) of the rod. The rod is initially motionless but is free to rotate around the pivot. A student will slide a disk of mass  $m_{disk}$  toward the rod with velocity  $v_0$  perpendicular to the rod, and the disk will stick to the rod a distance *x* from the pivot. The student wants the rod-disk system to end up with as much angular speed as possible.

(a) Suppose the rod is much more massive than the disk. To give the rod as much angular speed as possible, should the student make the disk hit the rod to the left of point *C*, at point *C*, or to the right of point *C*?

\_\_\_\_\_ To the left of C \_\_\_\_\_ At C \_\_\_\_\_ To the right of C

Briefly explain your reasoning without manipulating equations.

(b) On the Internet, a student finds the following equation for the postcollision angular speed  $\omega$  of the rod in this situation:  $\omega = \frac{m_{\text{disk}} x v_0}{I}$ . Regardless of whether this equation for angular speed is correct, does it agree with your qualitative reasoning in part (a) ? In other words, does this equation for  $\omega$  have the expected dependence as reasoned in part (a) ?

\_\_\_\_ Yes \_\_\_\_ No

Briefly explain your reasoning without deriving an equation for  $\omega$ .

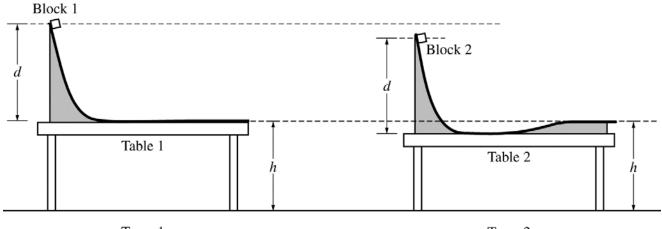
(c) Another student deriving an equation for the postcollision angular speed  $\omega$  of the rod makes a mistake and comes up with  $\omega = \frac{Ixv_0}{m_{\text{disk}}d^4}$ . Without deriving the correct equation, how can you tell that this equation is not plausible—in other words, that it does not make physical sense? Briefly explain your reasoning.

For parts (d) and (e), do NOT assume that the rod is much more massive than the disk.

- (d) Immediately before colliding with the rod, the disk's rotational inertia about the pivot is  $m_{disk} x^2$  and its angular momentum with respect to the pivot is  $m_{disk} v_0 x$ . Derive an equation for the postcollision angular speed  $\omega$  of the rod. Express your answer in terms of *d*,  $m_{disk}$ , *I*, *x*,  $v_0$ , and physical constants, as appropriate.
- (e) Consider the collision for which your equation in part (d) was derived, except now suppose the disk bounces backward off the rod instead of sticking to the rod. Is the postcollision angular speed of the rod when the disk bounces off it greater than, less than, or equal to the postcollision angular speed of the rod when the disk sticks to it?

\_\_\_\_ Greater than \_\_\_\_ Less than \_\_\_\_ Equal to

Briefly explain your reasoning.



Team 1

Team 2

4. (7 points, suggested time 13 minutes)

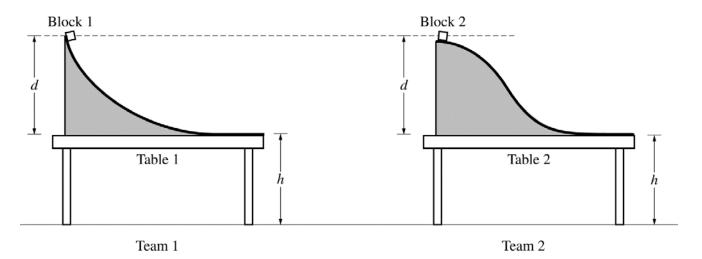
A physics class is asked to design a low-friction slide that will launch a block horizontally from the top of a lab table. Teams 1 and 2 assemble the slides shown above and use identical blocks 1 and 2, respectively. Both slides start at the same height d above the tabletop. However, team 2's table is lower than team 1's table. To compensate for the lower table, team 2 constructs the right end of the slide to rise above the tabletop so that the block leaves the slide horizontally at the same height h above the floor as does team 1's block (see figure above).

(a) Both blocks are released from rest at the top of their respective slides. Do block 1 and block 2 land the same distance from their respective tables?

\_\_\_\_ Yes \_\_\_\_ No

Justify your answer.

In another experiment, teams 1 and 2 use tables and low-friction slides with the same height. However, the two slides have different shapes, as shown below.



- (b) Both blocks are released from rest at the top of their respective slides at the same time.
  - i. Which block, if either, lands farther from its respective table?

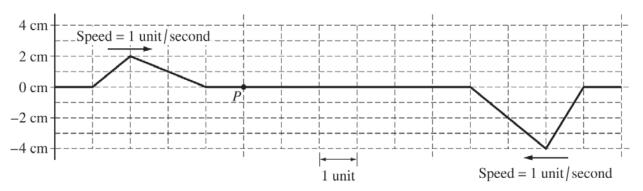
\_\_\_\_ Block 1 \_\_\_\_ Block 2 \_\_\_\_ The two blocks land the same distance from their respective tables.

Briefly explain your reasoning without manipulating equations.

ii. Which block, if either, hits the floor first?

\_\_\_\_Block 1 \_\_\_\_Block 2 \_\_\_\_The two blocks hit the floor at the same time.

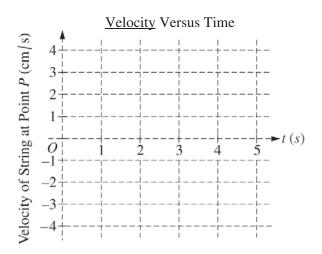
Briefly explain your reasoning without manipulating equations.



5. (7 points, suggested time 13 minutes)

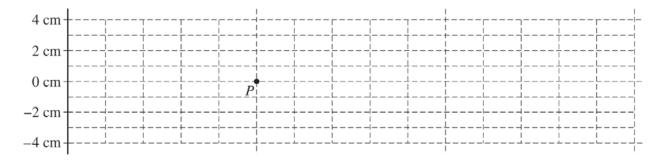
Two wave pulses are traveling in opposite directions on a string. The shape of the string at t = 0 is shown above. Each pulse is moving with a speed of one unit per second in the direction indicated.

(a) Between time t = 0 and t = 5 seconds, the entire left-hand pulse approaches and moves beyond point *P* on the string. On the coordinate axes below, plot the <u>velocity</u> of the piece of string located at point *P* as a function of time between t = 0 and t = 5 seconds.



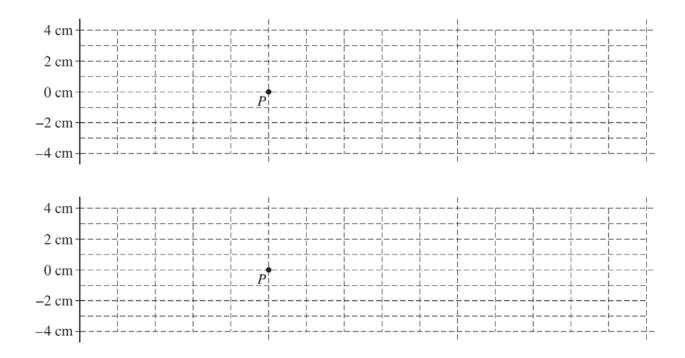
(b) At t = 5 s, the pulses completely overlap. On the grid provided below, sketch the shape of the entire string at t = 5 s.

<u>Note:</u> Do any scratch (practice) work on the grids on the following page. You will only be graded for the sketch made on the grid on this page.



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The grids below are provided for scratch work only. Sketches made below will NOT be graded.



#### STOP

#### END OF EXAM

2018



# AP Physics 1: Algebra-Based

# **Free-Response Questions**

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CONSTANTS AND CONVERSION FACTORS						
Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude,	$e = 1.60 \times 10^{-19} \text{ C}$				
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant,	$k = 1/4\pi\varepsilon_0 = 9.0 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2$				
Electron mass, $m_e = 9.11 \times 10^{-31} \text{ kg}$	Universal gravitational constant,	$G = 6.67 \times 10^{-11} \text{ m}^3/\text{kg}\cdot\text{s}^2$				
Speed of light, $c = 3.00 \times 10^8 \text{ m/s}$	Acceleration due to gravity at Earth's surface,	$g = 9.8 \text{ m/s}^2$				

### **AP<sup>®</sup> PHYSICS 1 TABLE OF INFORMATION**

	meter,	m	kelvin,	Κ	watt,	W	degree Celsius,	°C
UNIT	kilogram,	kg	hertz,	Hz	coulomb,	С		
SYMBOLS	second,	S	newton,	Ν	volt,	V		
	ampere,	А	joule,	J	ohm,	Ω		

	PREFIXES						
Factor	Prefix	Symbol					
10 <sup>12</sup>	tera	Т					
10 <sup>9</sup>	giga	G					
10 <sup>6</sup>	mega	М					
10 <sup>3</sup>	kilo	k					
10 <sup>-2</sup>	centi	С					
$10^{-3}$	milli	m					
10 <sup>-6</sup>	micro	μ					
10 <sup>-9</sup>	nano	n					
10 <sup>-12</sup>	pico	р					

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
θ	$0^{\circ}$	$30^{\circ}$	$37^{\circ}$	$45^{\circ}$	$53^{\circ}$	$60^{\circ}$	$90^{\circ}$
sin $ heta$	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
$\tan \theta$	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	∞

The following conventions are used in this exam.

- I. The frame of reference of any problem is assumed to be inertial unless otherwise stated.
- II. Assume air resistance is negligible unless otherwise stated.
- III. In all situations, positive work is defined as work done <u>on</u> a system.
- IV. The direction of current is conventional current: the direction in which positive charge would drift.
- V. Assume all batteries and meters are ideal unless otherwise stated.

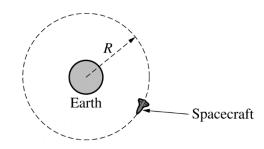
## **AP<sup>®</sup> PHYSICS 1 EQUATIONS**

MEC	HANICS	ELECTRICITY		
$v_x = v_{x0} + a_x t$ $x = x_0 + v_{x0}t + \frac{1}{2}a_x t^2$ $v_x^2 = v_{x0}^2 + 2a_x (x - x_0)$ $\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$ $ \vec{F}_f  \le \mu  \vec{F}_n $ $a_c = \frac{v^2}{r}$ $\vec{p} = m\vec{v}$	$a = \operatorname{acceleration} A$ $A = \operatorname{amplitude} A$ $d = \operatorname{distance} B$ $E = \operatorname{energy} f$ $f = \operatorname{frequency} F$ $F = \operatorname{force} B$ $I = \operatorname{rotational inertia} B$ $K = \operatorname{kinetic energy} B$ $k = \operatorname{spring constant} B$ $L = \operatorname{angular momentum} B$ $\ell = \operatorname{length} B$ $m = \operatorname{mass} B$ $P = \operatorname{power} B$ $p = \operatorname{momentum} B$ $r = \operatorname{radius or separation} B$	$\begin{aligned} \left  \vec{F}_E \right  &= k \left  \frac{q_1 q_2}{r^2} \right  \\ I &= \frac{\Delta q}{\Delta t} \\ R &= \frac{\rho \ell}{A} \\ I &= \frac{\Delta V}{R} \\ P &= I \Delta V \\ R_s &= \sum_i R_i \\ \frac{1}{R_p} &= \sum_i \frac{1}{R_i} \end{aligned}$	A = area F = force I = current $\ell = \text{length}$ P = power q = charge R = resistance r = separation t = time V = electric potential $\rho = \text{resistivity}$	
$\Delta \vec{p} = \vec{F} \Delta t$ $K = \frac{1}{2} m v^2$	T = period t = time U = potential energy V = volume v = speed	$\lambda = \frac{v}{f} \qquad f = v$	AVES frequency speed wavelength	
$\Delta E = W = F_{\parallel}d = Fd\cos\theta$ $P = \frac{\Delta E}{\Delta t}$	W =  work done on a system x = position y = height $\alpha = \text{angular acceleration}$ $\mu = \text{coefficient of friction}$	<b>GEOMETRY AND</b> Rectangle A = bh	<b>D TRIGONOMETRY</b> A = area C = circumference V = volume	
$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$ $\omega = \omega_0 + \alpha t$ $x = A\cos(2\pi ft)$	$\theta$ = angle $\rho$ = density $\tau$ = torque $\omega$ = angular speed	Triangle $A = \frac{1}{2}bh$ Circle $A = \pi r^{2}$	S = surface area b = base h = height $\ell = $ length w = width	
$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$ $\tau = r_{\perp}F = rF\sin\theta$	$\Delta U_g = mg \Delta y$ $T = \frac{2\pi}{\omega} = \frac{1}{f}$	$A = \pi r$ $C = 2\pi r$ Rectangular solid $V = \ell wh$	r = radius Right triangle $c^2 = a^2 + b^2$	
$L = I\omega$ $\Delta L = \tau \Delta t$ $K = \frac{1}{2}I\omega^{2}$	$T_{s} = 2\pi \sqrt{\frac{m}{k}}$ $T_{p} = 2\pi \sqrt{\frac{\ell}{g}}$	Cylinder $V = \pi r^2 \ell$ $S = 2\pi r \ell + 2\pi r^2$ Sphere	$\sin\theta = \frac{a}{c}$ $\cos\theta = \frac{b}{c}$ $\tan\theta = \frac{a}{b}$	
$\begin{vmatrix} \vec{F}_s \end{vmatrix} = k  \vec{x}  \\ U_s = \frac{1}{2} k x^2$	$\left \vec{F}_{g}\right  = G \frac{m_{1}m_{2}}{r^{2}}$ $\vec{g} = \frac{\vec{F}_{g}}{m}$	$V = \frac{4}{3}\pi r^3$ $S = 4\pi r^2$	$\frac{c}{b} = \frac{b}{b}$	
$ \rho = \frac{m}{V} $	$U_G = -\frac{Gm_1m_2}{r}$			

#### PHYSICS 1

Section II Time—1 hour and 30 minutes 5 Questions

**Directions:** Questions 1, 4, and 5 are short free-response questions that require about 13 minutes each to answer and are worth 7 points each. Questions 2 and 3 are long free-response questions that require about 25 minutes each to answer and are worth 12 points each. Show your work for each part in the space provided after that part.

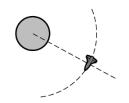


Note: Figure not drawn to scale.

1. (7 points, suggested time 13 minutes)

A spacecraft of mass *m* is in a clockwise circular orbit of radius *R* around Earth, as shown in the figure above. The mass of Earth is  $M_E$ .

(a) In the figure below, draw and label the forces (not components) that act on the spacecraft. Each force must be represented by a distinct arrow starting on, and pointing away from, the spacecraft.



Note: Figure not drawn to scale.

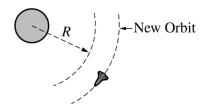
(b)

- i. Derive an equation for the orbital period T of the spacecraft in terms of m,  $M_E$ , R, and physical constants, as appropriate. If you need to draw anything other than what you have shown in part (a) to assist in your solution, use the space below. Do NOT add anything to the figure in part (a).
- ii. A second spacecraft of mass 2m is placed in a circular orbit with the same radius R. Is the orbital period of the second spacecraft greater than, less than, or equal to the orbital period of the first spacecraft?

\_\_\_\_ Greater than \_\_\_\_\_ Less than \_\_\_\_\_ Equal to

Briefly explain your reasoning.

(c) The first spacecraft is moved into a new circular orbit that has a radius greater than R, as shown in the figure below.



Note: Figure not drawn to scale.

Is the speed of the spacecraft in the new orbit greater than, less than, or equal to the original speed?

\_\_\_\_ Greater than \_\_\_\_ Less than \_\_\_\_ Equal to

Briefly explain your reasoning.

2. (12 points, suggested time 25 minutes)

A group of students prepare a large batch of conductive dough (a soft substance that can conduct electricity) and then mold the dough into several cylinders with various cross-sectional areas *A* and lengths  $\ell$ . Each student applies a potential difference  $\Delta V$  across the ends of a dough cylinder and determines the resistance *R* of the cylinder. The results of their experiments are shown in the table below.

Dough Cylinder	<i>A</i> (m <sup>2</sup> )	ℓ (m)	$\Delta V$ (V)	$R(\Omega)$	
1	0.00049	0.030	1.02	23.6	
2	0.00049	0.050	2.34	31.5	
3	0.00053	0.080	3.58	61.2	
4	0.00057	0.150	6.21	105	

(a) The students want to determine the resistivity of the dough cylinders.

i. Indicate below which quantities could be graphed to determine a value for the resistivity of the dough cylinders. You may use the remaining columns in the table above, as needed, to record any quantities (including units) that are not already in the table.

Vertical Axis: \_\_\_\_\_

Horizontal Axis:

ii. On the grid below, plot the appropriate quantities to determine the resistivity of the dough cylinders. Clearly scale and label all axes, including units as appropriate.

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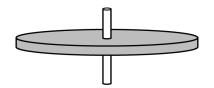
iii. Use the above graph to estimate a value for the resistivity of the dough cylinders.

(b) Another group of students perform the experiment described in part (a) but shape the dough into long rectangular shapes instead of cylinders. Will this change affect the value of the resistivity determined by the second group of students?

\_\_\_\_Yes \_\_\_\_No

Briefly justify your reasoning.

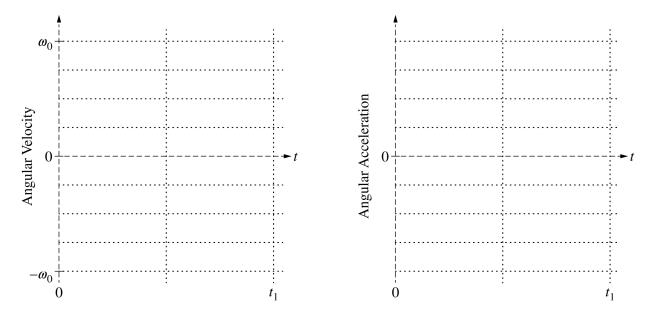
(c) Describe an experimental procedure to determine whether or not the resistivity of the dough cylinders depends on the temperature of the dough. Give enough detail so that another student could replicate the experiment. As needed, include a diagram of the experimental setup. Assume equipment usually found in a school physics laboratory is available.



3. (12 points, suggested time 25 minutes)

The disk shown above spins about the axle at its center. A student's experiments reveal that, while the disk is spinning, friction between the axle and the disk exerts a constant torque on the disk.

- (a) At time t = 0 the disk has an initial counterclockwise (positive) angular velocity  $\omega_0$ . The disk later comes to rest at time  $t = t_1$ .
  - i. On the grid at left below, sketch a graph that could represent the disk's angular velocity as a function of time t from t = 0 until the disk comes to rest at time  $t = t_1$ .
  - ii. On the grid at right below, sketch the disk's angular acceleration as a function of time t from t = 0 until the disk comes to rest at time  $t = t_1$ .

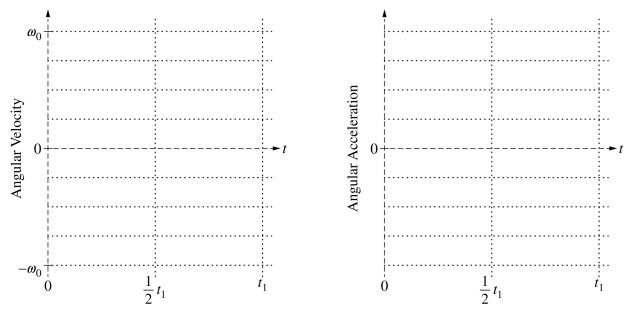


(b) The magnitude of the frictional torque exerted on the disk is  $\tau_0$ . Derive an equation for the rotational inertia *I* of the disk in terms of  $\tau_0$ ,  $\omega_0$ ,  $t_1$ , and physical constants, as appropriate.

(c) In another experiment, the disk again has an initial positive angular velocity  $\omega_0$  at time t = 0. At

time  $t = \frac{1}{2}t_1$ , the student starts dripping oil on the contact surface between the axle and the disk to reduce the friction. As time passes, more and more oil reaches that contact surface, reducing the friction even further.

- i. On the grid at left below, sketch a graph that could represent the disk's angular velocity as a function of time from t = 0 to  $t = t_1$ , which is the time at which the disk came to rest in part (a).
- ii. On the grid at right below, sketch the disk's angular acceleration as a function of time from t = 0 to  $t = t_1$ .



- (d) The student is trying to mathematically model the magnitude  $\tau$  of the torque exerted by the axle on the disk when the oil is present at times  $t > \frac{1}{2}t_1$ . The student writes down the following two equations, each of which includes a positive constant ( $C_1$  or  $C_2$ ) with appropriate units.
  - (1)  $\tau = C_1 \left( t \frac{1}{2} t_1 \right) \text{ (for } t > \frac{1}{2} t_1 \text{)}$

(2) 
$$\tau = \frac{C_2}{\left(t + \frac{1}{2}t_1\right)}$$
 (for  $t > \frac{1}{2}t_1$ )

Which equation better mathematically models this experiment?

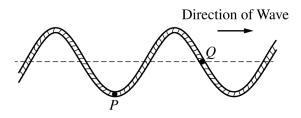
\_\_\_\_\_ Equation (1) \_\_\_\_\_ Equation (2)

Briefly explain why the equation you selected is plausible and why the other equation is not plausible.

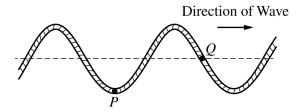
4. (7 points, suggested time 13 minutes)

A transverse wave travels to the right along a string.

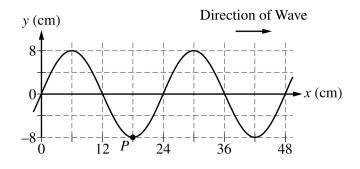
- (a) Two dots have been painted on the string. In the diagrams below, those dots are labeled P and Q.
  - i. The figure below shows the string at an instant in time. At the instant shown, dot *P* has maximum displacement and dot *Q* has zero displacement from equilibrium. At each of the dots *P* and *Q*, draw an arrow indicating the direction of the instantaneous velocity of that dot. If either dot has zero velocity, write "v = 0" next to the dot.



ii. The figure below shows the string at the same instant as shown in part (a)i. At each of the dots P and Q, draw an arrow indicating the direction of the instantaneous acceleration of that dot. If either dot has zero acceleration, write "a = 0" next to the dot.



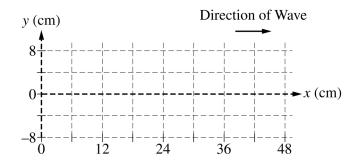
The figure below represents the string at time t = 0, the same instant as shown in part (a) when dot P is at its maximum displacement from equilibrium. For simplicity, dot Q is not shown.



(b)

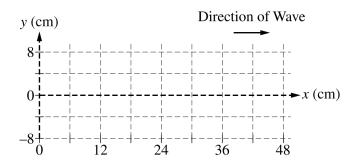
i. On the grid below, draw the string at a later time t = T/4, where T is the period of the wave.

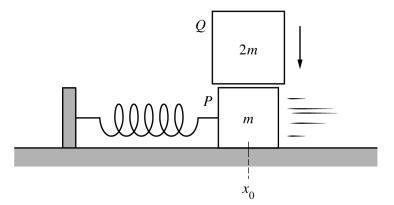
<u>Note:</u> Do any scratch (practice) work on the grid at the bottom of the page. Only the sketch made on the grid immediately below will be graded.



- ii. On your drawing above, draw a dot to indicate the position of dot *P* on the string at time t = T/4 and clearly label the dot with the letter *P*.
- (c) Now consider the wave at time t = T. Determine the distance traveled (not the displacement) by dot *P* between times t = 0 and t = T.

The grid below is provided for scratch work only. Sketches made below will not be graded.

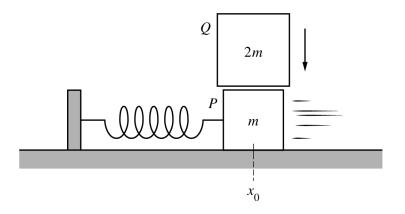




5. (7 points, suggested time 13 minutes)

Block *P* of mass *m* is on a horizontal, frictionless surface and is attached to a spring with spring constant *k*. The block is oscillating with period  $T_P$  and amplitude  $A_P$  about the spring's equilibrium position  $x_0$ . A second block *Q* of mass 2m is then dropped from rest and lands on block *P* at the instant it passes through the equilibrium position, as shown above. Block *Q* immediately sticks to the top of block *P*, and the two-block system oscillates with period  $T_{PQ}$  and amplitude  $A_{PQ}$ .

(a) Determine the numerical value of the ratio  $T_{PO}/T_P$ .



(b) The figure is reproduced above. How does the amplitude of oscillation  $A_{PQ}$  of the two-block system compare with the original amplitude  $A_P$  of block *P* alone?

In a clear, coherent paragraph-length response that may also contain diagrams and/or equations, explain your reasoning.

#### STOP

#### END OF EXAM

2019



# **AP<sup>°</sup> Physics 1: Algebra-Based** Free-Response Questions

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Electron mass, $m_e = 9.11 \times 10^{-31} \text{ kg}$	Universal gravitational constant,	$G = 6.67 \times 10^{-11} \text{ m}^3/\text{kg}\cdot\text{s}^2$				
Speed of light, $c = 3.00 \times 10^8 \text{ m/s}$	Acceleration due to gravity at Earth's surface,	$g = 9.8 \text{ m/s}^2$				

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	ampere,	А	joule,	J	ohm,	Ω		

PREFIXES						
Factor	Prefix	Symbol				
10 <sup>12</sup>	tera	Т				
10 <sup>9</sup>	giga	G				
10 <sup>6</sup>	mega	М				
10 <sup>3</sup>	kilo	k				
10 <sup>-2</sup>	centi	с				
10 <sup>-3</sup>	milli	m				
10 <sup>-6</sup>	micro	μ				
10 <sup>-9</sup>	nano	n				
10 <sup>-12</sup>	pico	р				

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
θ	$0^{\circ}$	$30^{\circ}$	$37^{\circ}$	$45^{\circ}$	$53^{\circ}$	$60^{\circ}$	$90^{\circ}$
sin $ heta$	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
$\tan \theta$	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	∞

The following conventions are used in this exam.

- I. The frame of reference of any problem is assumed to be inertial unless otherwise stated.
- II. Assume air resistance is negligible unless otherwise stated.
- III. In all situations, positive work is defined as work done <u>on</u> a system.
- IV. The direction of current is conventional current: the direction in which positive charge would drift.
- V. Assume all batteries and meters are ideal unless otherwise stated.

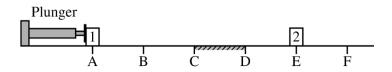
## **AP<sup>®</sup> PHYSICS 1 EQUATIONS**

MEC	HANICS	ELECTRICITY		
$v_x = v_{x0} + a_x t$ $x = x_0 + v_{x0}t + \frac{1}{2}a_x t^2$ $v_x^2 = v_{x0}^2 + 2a_x(x - x_0)$ $\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$ $ \vec{F}_f  \le \mu  \vec{F}_n $ $a_c = \frac{v^2}{r}$ $\vec{p} = m\vec{v}$	$a = \operatorname{acceleration} A$ $A = \operatorname{amplitude} A$ $d = \operatorname{distance} B$ $E = \operatorname{energy} f$ $f = \operatorname{frequency} F$ $F = \operatorname{force} B$ $I = \operatorname{rotational inertia} B$ $K = \operatorname{kinetic energy} B$ $k = \operatorname{spring constant} B$ $L = \operatorname{angular momentum} B$ $\ell = \operatorname{length} B$ $m = \operatorname{mass} B$ $P = \operatorname{power} B$ $p = \operatorname{momentum} B$ $r = \operatorname{radius or separation} B$	$\begin{aligned} \left  \vec{F}_E \right  &= k \left  \frac{q_1 q_2}{r^2} \right  \\ I &= \frac{\Delta q}{\Delta t} \\ R &= \frac{\rho \ell}{A} \\ I &= \frac{\Delta V}{R} \\ P &= I \Delta V \\ R_s &= \sum_i R_i \\ \frac{1}{R_p} &= \sum_i \frac{1}{R_i} \end{aligned}$	A = area F = force I = current $\ell = \text{length}$ P = power q = charge R = resistance r = separation t = time V = electric potential $\rho = \text{resistivity}$	
$\Delta \vec{p} = \vec{F} \Delta t$ $K = \frac{1}{2} m v^2$	T = period t = time U = potential energy V = volume v = speed	$\lambda = \frac{v}{f} \qquad f = v$	AVES frequency speed wavelength	
$\Delta E = W = F_{\parallel}d = Fd\cos\theta$ $P = \frac{\Delta E}{\Delta t}$	W = work done on a system x = position y = height $\alpha =$ angular acceleration w = coefficient of friction		<b>D TRIGONOMETRY</b> A = area C = circumference V = volume	
$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$ $\omega = \omega_0 + \alpha t$	$\mu = \text{ coefficient of friction}$ $\theta = \text{ angle}$ $\rho = \text{ density}$ $\tau = \text{ torque}$	Triangle $A = \frac{1}{2}bh$	S = surface area b = base h = height $\ell = $ length	
$x = A\cos(2\pi ft)$ $\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$	$\omega$ = angular speed $\Delta U_g = mg \Delta y$ $2\pi = 1$	Circle $A = \pi r^{2}$ $C = 2\pi r$ Besten cular solid	w = width r = radius	
$\tau = r_{\perp}F = rF\sin\theta$ $L = I\omega$ $\Delta L = \tau \Delta t$	$T = \frac{2\pi}{\omega} = \frac{1}{f}$ $T_s = 2\pi \sqrt{\frac{m}{k}}$	Rectangular solid $V = \ell wh$ Cylinder $V = \pi r^2 \ell$	Right triangle $c^2 = a^2 + b^2$ $\sin \theta = \frac{a}{c}$	
$K = \frac{1}{2}I\omega^2$ $\left \vec{F}_s\right  = k\left \vec{x}\right $	$T_p = 2\pi \sqrt{\frac{\ell}{g}}$ $\left \vec{F}_g\right  = G \frac{m_1 m_2}{r^2}$	$S = 2\pi r \ell + 2\pi r^{2}$ Sphere $V = \frac{4}{3}\pi r^{3}$ $S = 4\pi r^{2}$	$\cos\theta = \frac{b}{c}$ $\tan\theta = \frac{a}{b}$	
$U_s = \frac{1}{2}kx^2$ $\rho = \frac{m}{V}$	$\vec{g} = \frac{\vec{F}_g}{m}$ $U_G = -\frac{Gm_1m_2}{r}$	$S = 4\pi r^2$	$b = \frac{\theta}{b}$	

# PHYSICS 1

# Section II Time—1 hour and 30 minutes 5 Questions

**Directions:** Questions 1, 4, and 5 are short free-response questions that require about 13 minutes each to answer and are worth 7 points each. Questions 2 and 3 are long free-response questions that require about 25 minutes each to answer and are worth 12 points each. Show your work for each part in the space provided after that part.

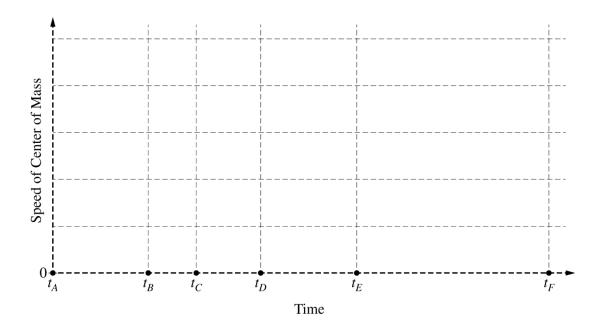


1. (7 points, suggested time 13 minutes)

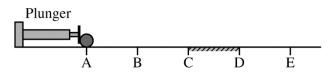
Identical blocks 1 and 2 are placed on a horizontal surface at points A and E, respectively, as shown. The surface is frictionless except for the region between points C and D, where the surface is rough. Beginning at time  $t_A$ ,

block 1 is pushed with a <u>constant</u> horizontal force from point A to point B by a mechanical plunger. Upon reaching point B, block 1 loses contact with the plunger and continues moving to the right along the horizontal surface toward block 2. Block 1 collides with and sticks to block 2 at point E, after which the two-block system continues moving across the surface, eventually passing point F.

(a) On the axes below, sketch the speed of the <u>center of mass</u> of the two-block system as a function of time, from time  $t_A$  until the blocks pass point F at time  $t_F$ . The times at which block 1 reaches points A through F are indicated on the time axis.



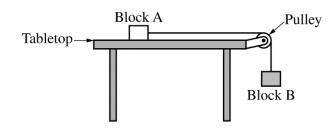
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(b) The plunger is returned to its original position, and both blocks are removed. A uniform solid sphere is placed at point A, as shown. The sphere is pushed by the plunger from point A to point B with a <u>constant</u> horizontal force that is directed toward the sphere's center of mass. The sphere loses contact with the plunger at point B and continues moving across the horizontal surface toward point E. In which interval(s), if any, does the sphere's angular momentum about its center of mass change? Check all that apply.

\_\_\_\_\_A to B \_\_\_\_B to C \_\_\_\_C to D \_\_\_\_D to E \_\_\_\_\_None

Briefly explain your reasoning.



2. (12 points, suggested time 25 minutes)

This problem explores how the relative masses of two blocks affect the acceleration of the blocks. Block A, of mass  $m_A$ , rests on a horizontal tabletop. There is negligible friction between block A and the tabletop. Block B, of mass  $m_B$ , hangs from a light string that runs over a pulley and attaches to block A, as shown above. The pulley has negligible mass and spins with negligible friction about its axle. The blocks are released from rest.

(a)

i. Suppose the mass of block A is much greater than the mass of block B. Estimate the magnitude of the acceleration of the blocks after release.

Briefly explain your reasoning without deriving or using equations.

ii. Now suppose the mass of block A is much <u>less</u> than the mass of block B. Estimate the magnitude of the acceleration of the blocks after release.

Briefly explain your reasoning without deriving or using equations.

(b) Now suppose neither block's mass is much greater than the other, but that they are not necessarily equal. The dots below represent block A and block B, as indicated by the labels. On each dot, draw and label the forces (not components) exerted on that block after release. Represent each force by a distinct arrow starting on, and pointing away from, the dot.





- (c) Derive an equation for the acceleration of the blocks after release in terms of  $m_A$ ,  $m_B$ , and physical constants, as appropriate. If you need to draw anything other than what you have shown in part (b) to assist in your solution, use the space below. Do NOT add anything to the figure in part (b).
- (d) Consider the scenario from part (a)(ii), where the mass of block A is much <u>less</u> than the mass of block B. Does your equation for the acceleration of the blocks from part (c) agree with your reasoning in part (a)(ii) ?

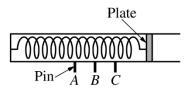
\_\_\_\_Yes \_\_\_\_No

Briefly explain your reasoning by addressing why, according to your equation, the acceleration becomes (or approaches) a certain value when  $m_A$  is much less than  $m_B$ .

(e) While the blocks are accelerating, the tension in the vertical portion of the string is  $T_1$ . Next, the pulley of negligible mass is replaced with a second pulley whose mass is not negligible. When the blocks are accelerating in this scenario, the tension in the vertical portion of the string is  $T_2$ . How do the two tensions compare to each other?

 $\_$   $T_2 > T_1$   $\_$   $T_2 = T_1$   $\_$   $T_2 < T_1$ 

Briefly explain your reasoning.



Sphere A B C

Figure 1. Uncompressed spring

Figure 2. Compressed spring

3. (12 points, suggested time 25 minutes)

A projectile launcher consists of a spring with an attached plate, as shown in Figure 1. When the spring is compressed, the plate can be held in place by a pin at any of three positions A, B, or C. For example, Figure 2 shows a steel sphere placed against the plate, which is held in place by a pin at position C. The sphere is launched upon release of the pin.

A student hypothesizes that the spring constant of the spring inside the launcher has the same value for different compression distances.

- (a) The student plans to test the hypothesis by launching the sphere using the launcher.
  - i. State a basic physics principle or law the student could use in designing an experiment to test the hypothesis.
  - ii. Using the principle or law stated in part (a)(i), determine an expression for the spring constant in terms of quantities that can be obtained from measurements made with equipment usually found in a school physics laboratory.
- (b) Design an experimental procedure to test the hypothesis <u>in which the student uses the launcher to launch the</u> <u>sphere</u>. Assume equipment usually found in a school physics laboratory is available.

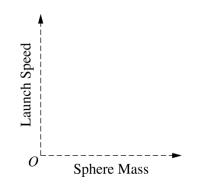
In the table below, list the quantities and associated symbols that would be measured in your experiment. Also list the equipment that would be used to measure each quantity. You do not need to fill in every row. If you need additional rows, you may add them to the space just below the table.

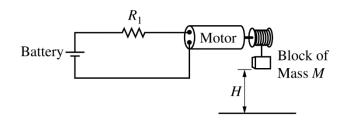
Quantity to be Measured	Symbol for Quantity	Equipment for Measurement

#### (b) Continued

Describe the overall procedure to be used to test the hypothesis that the spring constant of the spring inside the launcher has the same value for different compression distances, referring to the table. Provide enough detail so that another student could replicate the experiment, including any steps necessary to reduce experimental uncertainty. As needed, use the symbols defined in the table and/or include a simple diagram of the setup.

- (c) Describe how the experimental data could be analyzed to confirm or disconfirm the hypothesis that the spring constant of the spring inside the launcher has the same value for different compression distances.
- (d) Another student uses the launcher to consecutively launch several spheres that have the same diameter but different masses, one after another. Each sphere is launched from position A. Consider each sphere's launch speed, which is the speed of the sphere at the instant it loses contact with the plate. On the axes below, sketch a graph of launch speed as a function of sphere mass.





4. (7 points, suggested time 13 minutes)

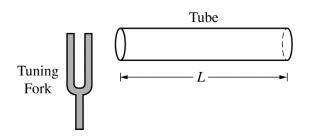
A motor is a device that when connected to a battery converts electrical energy into mechanical energy. The motor shown above is used to lift a block of mass M at constant speed from the ground to a height H above the ground in a time interval  $\Delta t$ . The motor has constant resistance and is connected in series with a resistor of resistance  $R_1$  and a battery.

Mechanical power, the rate at which mechanical work is done on the block, increases if the potential difference (voltage drop) between the two terminals of the motor increases.

- (a) Determine an expression for the mechanical power in terms of M, H,  $\Delta t$ , and physical constants, as appropriate.
- (b) Without *M* or *H* being changed, the time interval  $\Delta t$  can be decreased by adding one resistor of resistance  $R_2$ , where  $R_2 > R_1$ , to the circuit shown above. How should the resistor of resistance  $R_2$  be added to the circuit to decrease  $\Delta t$ ?

In parallel with	In parallel	In parallel with	In series with the battery,
the battery	with $R_1$	the motor	$R_1$ , and the motor

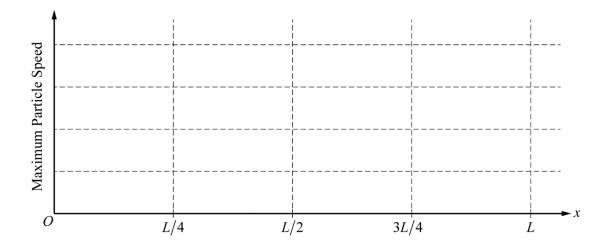
In a clear, coherent, paragraph-length response that may also contain figures and/or equations, justify why your selection would decrease  $\Delta t$ .



5. (7 points, suggested time 13 minutes)

A tuning fork vibrating at 512 Hz is held near one end of a tube of length L that is <u>open</u> at both ends, as shown above. The column of air in the tube resonates at its fundamental frequency. The speed of sound in air is 340 m/s.

- (a) Calculate the length *L* of the tube.
- (b) The column of air in the tube is still resonating at its fundamental frequency. On the axes below, sketch a graph of the maximum speed of air molecules as they oscillate in the tube, as a function of position x, from x = 0 (left end of tube) to x = L (right end of tube). (Ignore random thermal motion of the air molecules.)



(c) The right end of the tube is now capped shut, and the tube is placed in a chamber that is filled with another gas in which the speed of sound is 1005 m/s. Calculate the new fundamental frequency of the tube.

#### STOP

#### END OF EXAM



**AP**<sup>°</sup>

# AP<sup>°</sup> Physics 1: Algebra-Based

# **Free-Response Questions**

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# **AP® PHYSICS 1 TABLE OF INFORMATION**

# CONSTANTS AND CONVERSION FACTORS

	TO THE COLL PROPERTY	
Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude,	$e = 1.60 \times 10^{-19} \text{ C}$
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant,	$k = 1/4\pi\varepsilon_0 = 9.0 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2$
Electron mass, $m_e = 9.11 \times 10^{-31} \text{ kg}$	Universal gravitational constant,	$G = 6.67 \times 10^{-11} \text{ m}^3/\text{kg}\cdot\text{s}^2$
Speed of light, $c = 3.00 \times 10^8 \text{ m/s}$	Acceleration due to gravity at Earth's surface,	$g = 9.8 \text{ m/s}^2$

	meter,	m	kelvin,	Κ	watt,	W	degree Celsius,	°C
UNIT	kilogram,	kg	hertz,	Hz	coulomb,	С		
SYMBOLS	second,	S	newton,	Ν	volt,	V		
	ampere,	А	joule,	J	ohm,	Ω		

	PREFIXE	S
Factor	Prefix	Symbol
10 <sup>12</sup>	tera	Т
10 <sup>9</sup>	giga	G
10 <sup>6</sup>	mega	М
10 <sup>3</sup>	kilo	k
$10^{-2}$	centi	с
$10^{-3}$	milli	m
$10^{-6}$	micro	μ
10 <sup>-9</sup>	nano	n
10 <sup>-12</sup>	pico	р

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
θ	$0^{\circ}$	$30^{\circ}$	$37^{\circ}$	$45^{\circ}$	$53^{\circ}$	$60^{\circ}$	$90^{\circ}$
sin <b>θ</b>	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
tanθ	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	∞

The following conventions are used in this exam.

- I. The frame of reference of any problem is assumed to be inertial unless otherwise stated.
- II. Assume air resistance is negligible unless otherwise stated.
- III. In all situations, positive work is defined as work done <u>on</u> a system.
- IV. The direction of current is conventional current: the direction in which positive charge would drift.
- V. Assume all batteries and meters are ideal unless otherwise stated.

# **AP<sup>®</sup> PHYSICS 1 EQUATIONS**

MECI	HANICS	ELECTRICITY	
$v_x = v_{x0} + a_x t$ $x = x_0 + v_{x0}t + \frac{1}{2}a_x t^2$ $v_x^2 = v_{x0}^2 + 2a_x (x - x_0)$ $\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$ $ \vec{F}_f  \le \mu  \vec{F}_n $ $a_c = \frac{v^2}{r}$ $\vec{p} = m\vec{v}$	$a = \text{acceleration}$ $A = \text{amplitude}$ $d = \text{distance}$ $E = \text{energy}$ $f = \text{frequency}$ $F = \text{force}$ $I = \text{rotational inertia}$ $K = \text{kinetic energy}$ $k = \text{spring constant}$ $L = \text{angular momentum}$ $\ell = \text{length}$ $m = \text{mass}$ $P = \text{power}$ $p = \text{momentum}$ $r = \text{radius or separation}$ $T = \text{period}$	$\begin{aligned} \left  \vec{F}_{E} \right  &= k \left  \frac{q_{1}q_{2}}{r^{2}} \right  & A = \text{ area} \\ F &= \text{ force} \\ I &= \text{ current} \\ I &= \frac{\Delta q}{\Delta t} & \ell = \text{ length} \\ P &= \text{ power} \\ R &= \frac{\rho \ell}{A} & q = \text{ charge} \\ R &= \text{ resistance} \\ I &= \frac{\Delta V}{R} & r = \text{ separation} \\ P &= I \Delta V & V = \text{ electric pote} \\ R_{s} &= \sum_{i} R_{i} & \rho = \text{ resistivity} \\ \frac{1}{R_{p}} &= \sum_{i} \frac{1}{R_{i}} \end{aligned}$	ential
$\Delta \vec{p} = \vec{F} \Delta t$ $K = \frac{1}{2} m v^2$	t = time $U = potential energy$ $V = volume$ $v = speed$	$\lambda = \frac{v}{f}$ $WAVES$ $f = frequency$ $v = speed$ $\lambda = wavelength$	
$\Delta E = W = F_{\parallel}d = Fd\cos\theta$ $P = \frac{\Delta E}{\Delta t}$	W =  work done on a system x = position y = height $\alpha = \text{angular acceleration}$ $\mu = \text{coefficient of friction}$	GEOMETRY AND TRIGONOMETRRectangle $A = area$ $A = bh$ $C = circumferenceV = volumeV = volumeTriangleS = surface area$	
$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$ $\omega = \omega_0 + \alpha t$ $x = A\cos(2\pi ft)$	$\theta$ = angle $\rho$ = density $\tau$ = torque $\omega$ = angular speed	$A = \frac{1}{2}bh$ $A = \frac{1}{2}bh$ $b = base$ $h = height$ $\ell = length$ $w = width$ $A = \pi r^{2}$ $r = radius$	
$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$ $\tau = r_{\perp}F = rF\sin\theta$ $L = I\omega$	$\Delta U_g = mg \Delta y$ $T = \frac{2\pi}{\omega} = \frac{1}{f}$ $\boxed{m}$	$C = 2\pi r$ Rectangular solid $V = \ell wh$ Right triangle $c^2 = a^2 + b^2$	
$\Delta L = \tau \Delta t$ $K = \frac{1}{2}I\omega^2$	$T_{s} = 2\pi \sqrt{\frac{m}{k}}$ $T_{p} = 2\pi \sqrt{\frac{\ell}{g}}$	Cylinder $V = \pi r^2 \ell$ $S = 2\pi r \ell + 2\pi r^2$ Sphere $\sin \theta = \frac{a}{c}$ $\cos \theta = \frac{b}{c}$ $\tan \theta = \frac{a}{b}$	
$\begin{vmatrix}  \vec{F}_s  = k  \vec{x}  \\ U_s = \frac{1}{2} k x^2 \\ \rho = \frac{m}{V} \end{aligned}$	$\begin{vmatrix} \vec{F}_g \end{vmatrix} = G \frac{m_1 m_2}{r^2}$ $\vec{g} = \frac{\vec{F}_g}{m}$ $U_G = -\frac{G m_1 m_2}{r}$	$V = \frac{4}{3}\pi r^{3}$ $S = 4\pi r^{2}$ $\theta = 90^{\circ}$	a
	$U_G = -\frac{r}{r}$		

#### Begin your response to **QUESTION 1** on this page.

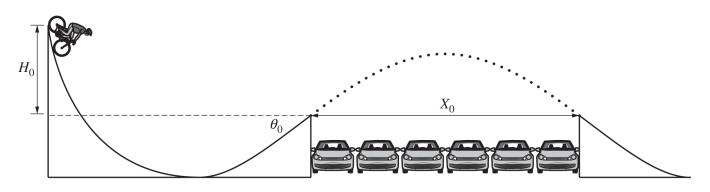
#### PHYSICS 1

#### **SECTION II**

#### Time—1 hour and 30 minutes

#### **5** Questions

**Directions:** Questions 1, 4, and 5 are short free-response questions that require about 13 minutes each to answer and are worth 7 points each. Questions 2 and 3 are long free-response questions that require about 25 minutes each to answer and are worth 12 points each. Show your work for each part in the space provided after that part.



Note: Figure not drawn to scale.

1. (7 points, suggested time 13 minutes)

A stunt cyclist builds a ramp that will allow the cyclist to coast down the ramp and jump over several parked cars, as shown above. To test the ramp, the cyclist starts from rest at the top of the ramp, then leaves the ramp, jumps over six cars, and lands on a second ramp.

 $H_0$  is the vertical distance between the top of the first ramp and the launch point.

 $\theta_0$  is the angle of the ramp at the launch point from the horizontal.

 $X_0$  is the horizontal distance traveled while the cyclist and bicycle are in the air.

 $m_0$  is the combined mass of the stunt cyclist and bicycle.

(a) Derive an expression for the distance  $X_0$  in terms of  $H_0$ ,  $\theta_0$ ,  $m_0$ , and physical constants, as appropriate.

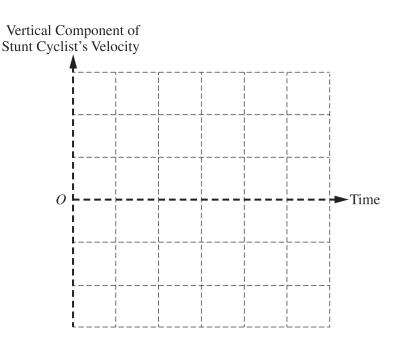
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### Continue your response to **QUESTION 1** on this page.

(b) If the vertical distance between the top of the first ramp and the launch point were  $2H_0$  instead of  $H_0$ , with no other changes to the first ramp, what is the maximum number of cars that the stunt cyclist could jump over? Justify your answer, using the expression you derived in part (a).

(c) On the axes below, sketch a graph of the vertical component of the stunt cyclist's velocity as a function of time from immediately after the cyclist leaves the ramp to immediately before the cyclist lands on the second ramp. On the vertical axis, clearly indicate the initial and final vertical velocity components in terms of  $H_0$ ,  $\theta_0$ ,  $m_0$ , and physical constants, as appropriate. Take the positive direction to be upward.



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Begin your response to **QUESTION 2** on this page.



2. (12 points, suggested time 25 minutes)

A group of students is investigating how the thickness of a plastic rod affects the maximum force  $F_{\text{max}}$  with which the rod can be pulled without breaking. Two students are discussing models to represent how  $F_{\text{max}}$  depends on rod thickness.

Student A claims that  $F_{\text{max}}$  is directly proportional to the radius of the rod.

Student B claims that  $F_{\text{max}}$  is directly proportional to the cross-sectional area of the rod—the area of the base of the cylinder, shaded gray in the figure above.

(a) The students have a collection of many rods of the same material. The rods are all the same length but come in a range of six different thicknesses. Design an experimental procedure to determine which student's model, if either, correctly represents how  $F_{\text{max}}$  depends on rod thickness.

In the table below, list the quantities that would be measured in your experiment. Define a symbol to represent each quantity, and also list the equipment that would be used to measure each quantity. You do not need to fill in every row. If you need additional rows, you may add them to the space just below the table.

Symbol for Quantity	Equipment for Measurement
	Symbol for Quantity

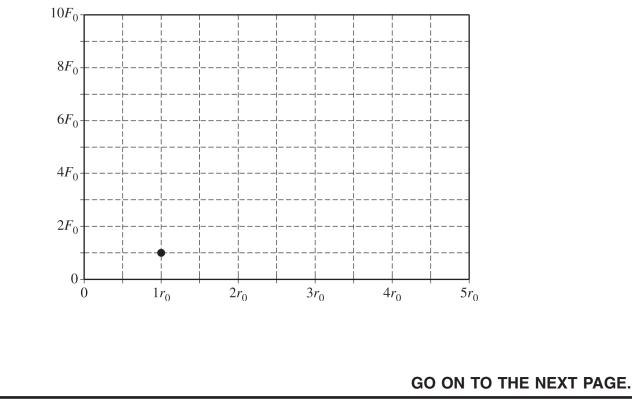
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#### Continue your response to **QUESTION 2** on this page.

Describe the overall procedure to be used, referring to the table. Provide enough detail so that another student could replicate the experiment, including any steps necessary to reduce experimental uncertainty. As needed, use the symbols defined in the table and/or include a simple diagram of the setup.

(b) For a rod of radius  $r_0$ , it is determined that  $F_{\text{max}}$  is  $F_0$ , as indicated by the dot on the grid below. On the grid, draw and label graphs corresponding to the two students' models of the dependence of  $F_{\text{max}}$  on rod radius. Clearly label each graph "A" or "B," corresponding to the appropriate model.



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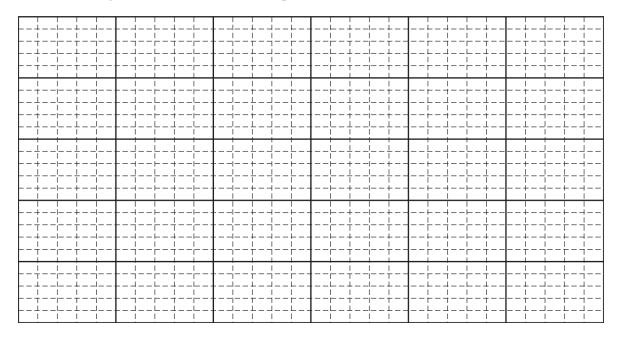
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Continue your response to **QUESTION 2** on this page.

The table below shows results of measurements taken by another group of students for rods of different thicknesses.

Rod radius (mm)	0.5	1.0	1.5	2.0	2.5
$F_{\max}$ (N)	40	120	320	520	900

(c) On the grid below, plot the data points from the table. Clearly scale and label all axes, including units. Draw either a straight line or a curve that best represents the data.



(d) Which student's model is more closely represented by the evidence shown in the graph you drew in part (c) ?

\_\_\_\_\_ Student A's model:  $F_{\text{max}}$  is directly proportional to the radius of the rod.

\_\_\_\_\_ Student B's model:  $F_{\text{max}}$  is directly proportional to the cross-sectional area of the rod.

Explain your reasoning.

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#### Begin your response to **QUESTION 3** on this page.

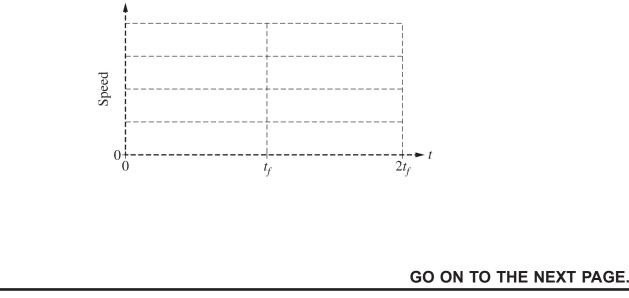
#### 3. (12 points, suggested time 25 minutes)

(a) A student of mass  $M_S$ , standing on a smooth surface, uses a stick to push a disk of mass  $M_D$ . The student exerts a constant horizontal force of magnitude  $F_H$  over the time interval from time t = 0 to  $t = t_f$  while pushing the disk. Assume there is negligible friction between the disk and the surface.

i. Assuming the disk begins at rest, determine an expression for the final speed  $v_D$  of the disk relative to the surface. Express your answer in terms of  $F_H$ ,  $t_f$ ,  $M_S$ ,  $M_D$ , and physical constants, as appropriate.

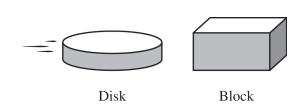
ii. Assume there is negligible friction between the student's shoes and the surface. After time  $t_f$ , the student slides with speed  $v_S$ . Derive an equation for the ratio  $v_D / v_S$ . Express your answer in terms of  $M_S$ ,  $M_D$ , and physical constants, as appropriate.

(b) Assume that the student's mass is greater than that of the disk  $(M_S > M_D)$ . On the grid below, sketch graphs of the speeds of both the student and the disk as functions of time t between t = 0 and  $t = 2t_f$ . Assume that neither the disk nor the student collides with anything after  $t = t_f$ . On the vertical axis, label  $v_D$  and  $v_S$ . Label the graphs "S" and "D" for the student and the disk, respectively.



Use a pencil or pen with black or dark blue ink only. Do NOT write your name. Do NOT write outside the box.

Continue your response to **QUESTION 3** on this page.



(c) The disk is now moving at a constant speed  $v_1$  on the surface toward a block of mass  $M_B$ , which is at rest on the surface, as shown above. The disk and block collide head-on and stick together, and the center of mass of the disk-block system moves with speed  $v_{cm}$ .

- i. Suppose the mass of the disk is much <u>greater</u> than the mass of the block. Estimate the velocity of the center of mass of the disk-block system. Explain how you arrived at your prediction without deriving it mathematically.
- ii. Suppose the mass of the disk is much <u>less</u> than the mass of the block. Estimate the velocity of the center of mass of the disk-block system. Explain how you arrived at your prediction without deriving it mathematically.
- iii. Now suppose that neither object's mass is much greater than the other but that they are not necessarily equal. Derive an equation for  $v_{cm}$ . Express your answer in terms of  $v_1$ ,  $M_D$ ,  $M_B$ , and physical constants, as appropriate.
- iv. Consider the scenario from part (c)(i), where the mass of the disk was much greater than the mass of the block. Does your equation for  $v_{cm}$  from part (c)(iii) agree with your reasoning from part (c)(i) ?

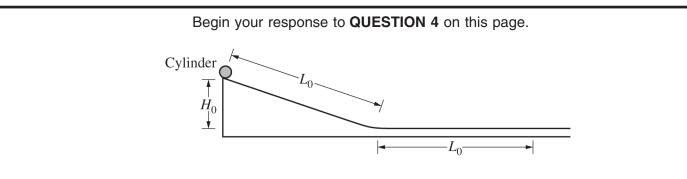
\_\_\_\_Yes \_\_\_\_No

Explain your reasoning by addressing why, according to your equation,  $v_{cm}$  becomes (or approaches) a certain value when  $M_D$  is much greater than  $M_B$ .

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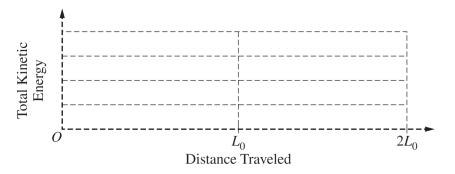
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4. (7 points, suggested time 13 minutes)

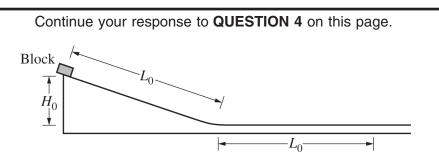
A cylinder of mass  $m_0$  is placed at the top of an incline of length  $L_0$  and height  $H_0$ , as shown above, and released from rest. The cylinder rolls without slipping down the incline and then continues rolling along a horizontal surface.

(a) On the grid below, sketch a graph that represents the total kinetic energy of the cylinder as a function of the distance traveled by the cylinder as it rolls down the incline and continues to roll across the horizontal surface.



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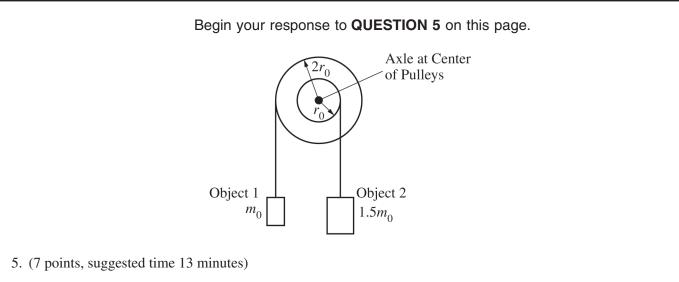
The cylinder is again placed at the top of the incline. A block, also of mass  $m_0$ , is placed at the top of a separate rough incline of length  $L_0$  and height  $H_0$ , as shown above. When the cylinder and block are released at the same instant, the cylinder begins to roll without slipping while the block begins to accelerate uniformly. The cylinder and the block reach the bottoms of their respective inclines with the same translational speed.

(b) In terms of energy, explain why the two objects reach the bottom of their respective inclines with the same translational speed. Provide your answer in a clear, coherent paragraph-length response that may also contain figures and/or equations.

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Two pulleys with different radii are attached to each other so that they rotate together about a horizontal axle through their common center. There is negligible friction in the axle. Object 1 hangs from a light string wrapped around the larger pulley, while object 2 hangs from another light string wrapped around the smaller pulley, as shown in the figure above.

 $m_0$  is the mass of object 1.

 $1.5m_0$  is the mass of object 2.

 $r_0$  is the radius of the smaller pulley.

 $2r_0$  is the radius of the larger pulley.

(a) At time t = 0, the pulleys are released from rest and the objects begin to accelerate.

i. Derive an expression for the magnitude of the net torque exerted on the objects-pulleys system about the axle after the pulleys are released. Express your answer in terms of  $m_0$ ,  $r_0$ , and physical constants, as appropriate.

ii. Object 1 accelerates downward after the pulleys are released. Briefly explain why.

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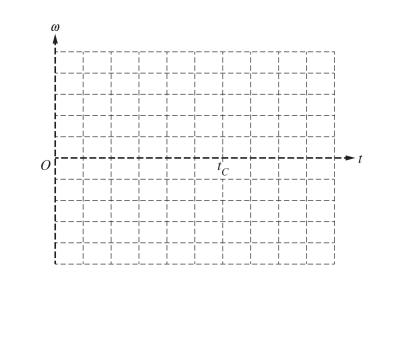
#### Continue your response to **QUESTION 5** on this page.

(b) At a later time  $t = t_C$ , the string of object 1 is cut while the objects are still moving and the pulley is still rotating. Immediately after the string is cut, how do the directions of the angular velocity and angular acceleration of the pulley compare to each other?

\_\_\_\_ Same direction \_\_\_\_ Opposite directions

Briefly explain your reasoning.

(c) On the axes below, sketch a graph of the angular velocity  $\omega$  of the system consisting of the two pulleys as a function of time *t*. Include the entire time interval shown. The pulleys are released at t = 0, and the string is cut at  $t = t_c$ .



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END OF EXAM

2022

**AP**<sup>°</sup>

# **AP<sup>°</sup> Physics 1: Algebra-Based** Free-Response Questions

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# **AP® PHYSICS 1 TABLE OF INFORMATION**

# CONSTANTS AND CONVERSION FACTORS

	TO THE COLL PROPERTY	
Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude,	$e = 1.60 \times 10^{-19} \text{ C}$
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant,	$k = 1/4\pi\varepsilon_0 = 9.0 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2$
Electron mass, $m_e = 9.11 \times 10^{-31} \text{ kg}$	Universal gravitational constant,	$G = 6.67 \times 10^{-11} \text{ m}^3/\text{kg}\cdot\text{s}^2$
Speed of light, $c = 3.00 \times 10^8 \text{ m/s}$	Acceleration due to gravity at Earth's surface,	$g = 9.8 \text{ m/s}^2$

	meter,	m	kelvin,	Κ	watt,	W	degree Celsius,	°C
UNIT	kilogram,	kg	hertz,	Hz	coulomb,	С		
SYMBOLS	second,	S	newton,	Ν	volt,	V		
	ampere,	А	joule,	J	ohm,	Ω		

	PREFIXE	S
Factor	Prefix	Symbol
10 <sup>12</sup>	tera	Т
10 <sup>9</sup>	giga	G
10 <sup>6</sup>	mega	М
10 <sup>3</sup>	kilo	k
$10^{-2}$	centi	с
$10^{-3}$	milli	m
$10^{-6}$	micro	μ
10 <sup>-9</sup>	nano	n
10 <sup>-12</sup>	pico	р

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
θ	$0^{\circ}$	$30^{\circ}$	$37^{\circ}$	$45^{\circ}$	$53^{\circ}$	$60^{\circ}$	$90^{\circ}$
sin <b>θ</b>	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
tanθ	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	∞

The following conventions are used in this exam.

- I. The frame of reference of any problem is assumed to be inertial unless otherwise stated.
- II. Assume air resistance is negligible unless otherwise stated.
- III. In all situations, positive work is defined as work done <u>on</u> a system.
- IV. The direction of current is conventional current: the direction in which positive charge would drift.
- V. Assume all batteries and meters are ideal unless otherwise stated.

#### **MECHANICS**

$$\begin{split} v_x &= v_{x0} + a_x t & a = \operatorname{acceleration} \\ A &= \operatorname{amplitude} \\ x &= x_0 + v_{x0}t + \frac{1}{2}a_x t^2 & E = \operatorname{energy} \\ f &= \operatorname{frequency} \\ r_x^2 &= v_{x0}^2 + 2a_x(x - x_0) & F = \operatorname{force} \\ \overline{a} &= \sum \frac{\overline{F}}{m} = \frac{\overline{F}_{mer}}{m} & K = \operatorname{kinetic energy} \\ k &= \operatorname{spring constant} \\ |\overline{F}_f| &\leq \mu |\overline{F}_n| & L = \operatorname{angular momentum} \\ \ell &= \operatorname{length} \\ a_c &= \frac{v^2}{r} & P = \operatorname{power} \\ p &= \operatorname{momentum} \\ \overline{p} &= m\overline{v} & r = \operatorname{radius or separation} \\ \overline{\Delta}\overline{p} &= \overline{F} \Delta t & t = \operatorname{time} \\ U &= \operatorname{potential energy} \\ K &= \frac{1}{2}mv^2 & V = \operatorname{volume} \\ v &= \operatorname{speed} \\ \Delta E &= W &= F_{\parallel}d = Fd\cos\theta & W = \operatorname{work done on a system} \\ x &= \operatorname{position} \\ P &= \frac{\Delta E}{\Delta t} & \tau = \operatorname{time} \\ U &= \operatorname{potential energy} \\ \omega &= \omega_0 + \omega_0 t + \frac{1}{2}\alpha t^2 & \theta = \operatorname{angle} \\ \rho &= \operatorname{density} \\ \omega &= \omega_0 + \alpha t & \tau = \operatorname{torque} \\ x &= \operatorname{Acos}(2\pi ft) & \Omega \\ \overline{\alpha} &= \sum \frac{\overline{T}}{I} &= \frac{\overline{\tau}_{ner}}{I} \\ \tau &= r_1 F = rF \sin\theta & T = \frac{2\pi}{\omega} = \frac{1}{f} \\ L &= I\omega & T_s &= 2\pi \sqrt{\frac{m}{k}} \\ K &= \frac{1}{2}I\omega^2 & I_s &= 2\pi \sqrt{\frac{k}{g}} \\ |\overline{F}_s| &= k|\overline{x}| & |\overline{F}_s| &= G \frac{m_1 m_2}{r^2} \\ U_s &= \frac{1}{2}kx^2 & \overline{g} &= \frac{\overline{F}_g}{m} \\ \rho &= \frac{m}{V} & U_G &= -\frac{Gm_1 m_2}{r} \\ \end{split}$$

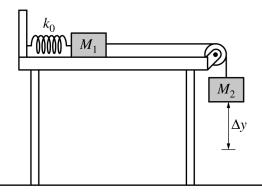
 $\frac{1}{f}$ 

GEOMETRY AND	FRIGONOMETRY
Rectangle A = bh Triangle	A = area C = circumference V = volume S = surface area
$A = \frac{1}{2}bh$ Circle $A = \pi r^{2}$ $C = 2\pi r$	b = base h = height $\ell = length$ w = width r = radius
$C = 2\pi r$ Rectangular solid $V = \ell wh$ Cylinder	Right triangle $c^2 = a^2 + b^2$ $\sin \theta = \frac{a}{2}$
$V = \pi r^2 \ell$ $S = 2\pi r \ell + 2\pi r^2$	$\sin\theta = \frac{a}{c}$ $\cos\theta = \frac{b}{c}$ $\tan\theta = \frac{a}{c}$
Sphere $V = \frac{4}{3}\pi r^{3}$ $S = 4\pi r^{2}$	$\tan \theta = \frac{a}{b}$ $c$ $\theta = 90^{\circ}$

#### Begin your response to **QUESTION 1** on this page.

# PHYSICS 1 SECTION II Time—1 hour and 30 minutes 5 Questions

**Directions:** Questions 1, 4, and 5 are short free-response questions that require about 13 minutes each to answer and are worth 7 points each. Questions 2 and 3 are long free-response questions that require about 25 minutes each to answer and are worth 12 points each. Show your work for each part in the space provided after that part.



#### 1. (7 points, suggested time 13 minutes)

Two blocks are connected by a string that passes over a pulley, as shown above. Block 1 is on a horizontal surface and is attached to a spring that is at its unstretched length. Frictional forces are negligible in the pulley's axle and between the block and the surface. Block 2 is released from rest and moves downward before momentarily coming to rest.

 $k_0$  is the spring constant of the spring.

 $M_1$  is the mass of block 1.

 $M_2$  is the mass of block 2.

 $\Delta y$  is the distance block 2 moves before momentarily coming to rest.

# GO ON TO THE NEXT PAGE.

#### Continue your response to **QUESTION 1** on this page.

(a)

i. Block 2 starts from rest and speeds up, then it slows down and momentarily comes to rest at a position below its initial position. In terms of <u>only</u> the forces directly exerted on block 2, explain why block 2 initially speeds up and explain why it slows down to a momentary stop.

ii. Derive an expression for the distance  $\Delta y$  that block 2 travels before momentarily coming to rest. Express your answer in terms of  $k_0$ ,  $M_1$ ,  $M_2$ , and physical constants, as appropriate.

(b) Indicate whether the total mechanical energy of the blocks-spring-Earth system changes as block 2 moves downward.

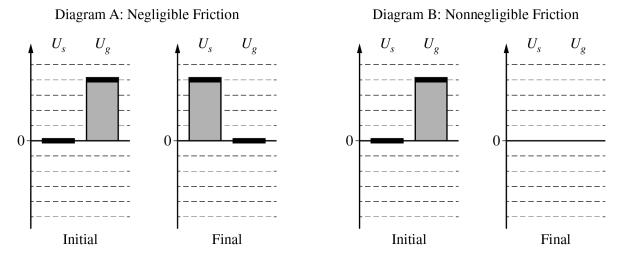
\_ Changes \_\_\_\_ Does not change

Briefly explain your reasoning.

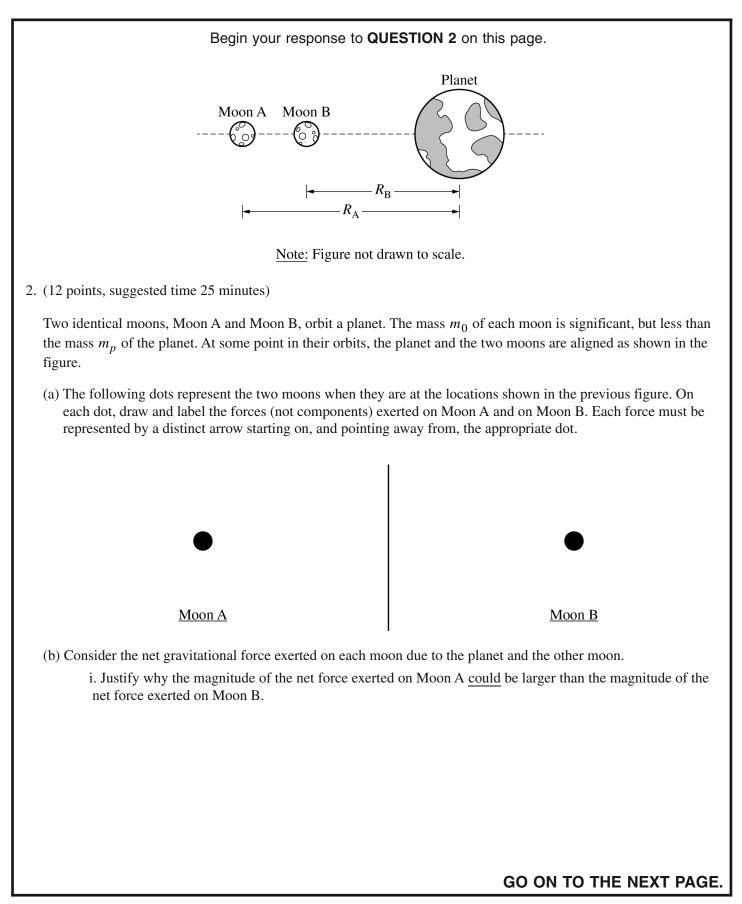
#### Continue your response to **QUESTION 1** on this page.

Consider the system that includes the spring, Earth, both blocks, and the string, but not the surface. Let the initial state be when the blocks are at rest just before they start moving, and let the final state be when the blocks first come momentarily to rest. Diagram A at left below is a bar chart that represents the energies in the scenario where there is negligible friction between block 1 and the surface.

The shaded-in bars in the energy bar charts represent the potential energy of the spring and the gravitational potential energy of the blocks-Earth system,  $U_s$  and  $U_g$ , respectively, in the initial and final states. Positive energy values are above the zero-point line ("0") and negative energy values are below the zero-point line.



- (c) Complete diagram B (at right above) for the scenario in which friction is nonnegligible. The energies for the initial state are already provided. Shade in the energies in the final state using the same scale as in diagram A.
- Shaded regions should start at the solid line representing the zero-point line.
- Represent any energy that is equal to zero with a distinct line on the zero-point line.



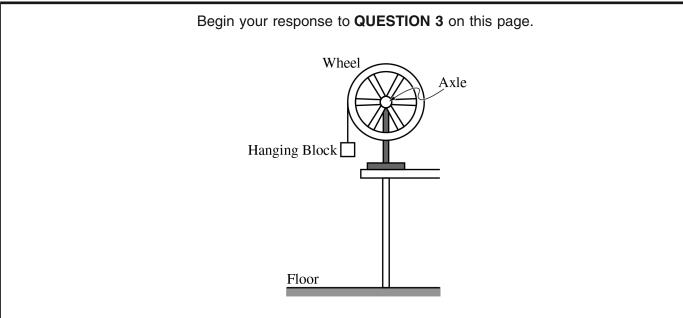
Continue your response to **QUESTION 2** on this page.

ii. Justify why the magnitude of the net force exerted on Moon B <u>could</u> be larger than the magnitude of the net force exerted on Moon A.

- (c) Derive expressions for both of the following quantities. Express your answers in terms of  $m_0$ ,  $m_p$ ,  $R_A$ ,  $R_B$ , and physical constants, as appropriate.
- The net force  $F_A$  exerted on Moon A

• The net force  $F_{\rm B}$  exerted on Moon B

(d) 	Continue your response to <b>QUESTION 2</b> on this page.
YesNo Explain your reasoning. ii. Could the expressions in part (c) support your reasoning in part (b)(ii) ? YesNo Explain your reasoning.	(d)
Explain your reasoning.	i. Could the expressions in part (c) support your reasoning in part (b)(i) ?
ii. Could the expressions in part (c) support your reasoning in part (b)(ii) ? YesNo Explain your reasoning.	Yes No
YesNo Explain your reasoning.	Explain your reasoning.
YesNo Explain your reasoning.	
YesNo Explain your reasoning.	$\therefore$ Could the engraced in part (a) suggest some recessing in part (b)( $\vdots$ ) ?
Explain your reasoning.	
GO ON TO THE NEXT PAGE.	Explain your reasoning.
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#### 3. (12 points, suggested time 25 minutes)

A wheel is mounted on a horizontal axle. A light string is attached to the wheel's rim and wrapped around it several times, and a small block is attached to the free end of the string, as shown in the figure. When the block is released from rest and begins to fall, the wheel begins to rotate with negligible friction.

Two students are discussing how different forms of energy change as the block falls. One student says that the kinetic energy of the block increases as it falls. The second student says that this is because gravitational potential energy is converted to kinetic energy. The students decide to test whether the decrease in gravitational potential energy is equal to the increase in the block's kinetic energy from when the block starts moving to immediately before it reaches the floor.

#### Continue your response to **QUESTION 3** on this page.

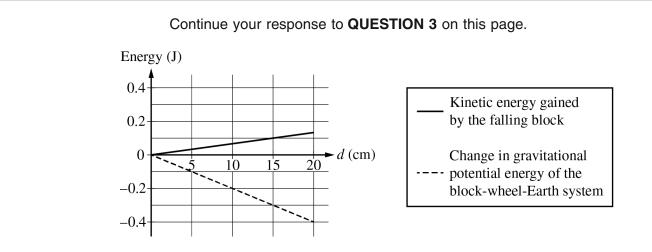
(a) Design an experimental procedure that the students could use to compare the increase in the block's translational kinetic energy with the decrease in the gravitational potential energy of the block-Earth system as the block falls.

In the table, list the quantities that would be measured in your experiment. Define a symbol to represent each quantity and list the equipment that would be used to measure each quantity. You do not need to fill in every row. If you need additional rows, you may add them to the space just below the table.

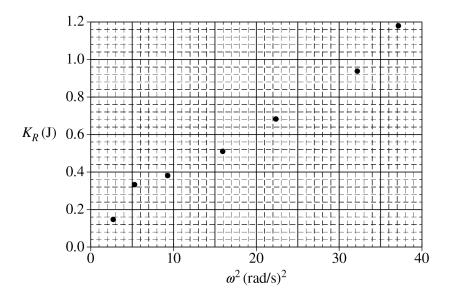
In the space to the right of the table, describe the overall procedure. Provide enough detail so that another student could replicate the experiment, including any steps necessary to reduce experimental uncertainty. As needed, use the symbols defined in the table.

If needed, you may include a simple diagram of the setup with your procedure.

Quantity to Be Measured	Symbol for Quantity	Equipment for Measurement	Procedure (and diagram, if needed)
(b) Evploi	n how the	studente could à	latermine the kinetic energy of the block immediately before it reaches the
			letermine the kinetic energy of the block immediately before it reaches the licated in the table in part (a).



- (c) The graph above represents both the change in the gravitational potential energy of the block-wheel-Earth system and the translational kinetic energy gained by the block as functions of the block's falling distance *d*. On the graph, draw a line or curve to represent the rotational kinetic energy of the wheel as a function of the block's falling distance *d*.
- (d) The students also measure the angular velocity  $\omega$  of the wheel as the block falls and determine the rotational kinetic energy  $K_R$  of the wheel. The students then make a graph of  $K_R$  as a function of  $\omega^2$ , as shown.



i. On the above graph, draw a straight line that best represents the data.

ii. Using the line you drew for part (d)(i), calculate an experimental value for the rotational inertia of the wheel.

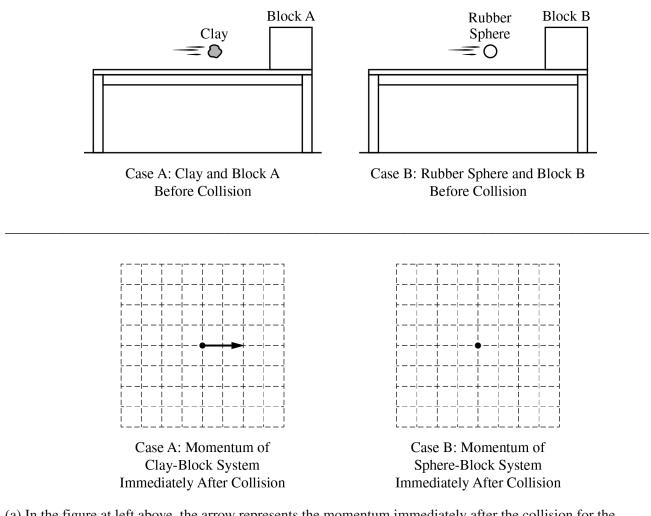
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#### Begin your response to **QUESTION 4** on this page.

4. (7 points, suggested time 13 minutes)

A student has a piece of clay and a rubber sphere, both of the same mass. Both objects are thrown horizontally at the same speed at identical blocks that are at rest at the edge of identical tables, as shown, where friction between the blocks and the table is negligible. After the collisions, both blocks fall to the floor.

In Case A, the clay sticks to Block A after the collision. In Case B, the rubber sphere bounces off of Block B after the collision.



(a) In the figure at left above, the arrow represents the momentum immediately after the collision for the clay-block system in Case A. In the figure at right above, draw an arrow starting on the dot to represent the momentum of the sphere-block system immediately after the collision in Case B. If the momentum is zero, write "zero" next to the dot. The momentum, if it is not zero, must be represented by an arrow starting on, and pointing away from, the dot. The length of the vector, if not zero, should reflect the magnitude of the momentum relative to Case A.

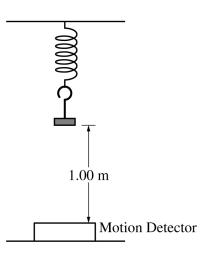
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Continue your response to **QUESTION 4** on this page.

(b) After the clay and Block A collide, Block A lands a horizontal distance  $d_A$  from the edge of the table. Does Block B land on the floor at a horizontal distance from the edge of the table that is greater than, less than, or equal to  $d_A$ ? In a clear, coherent, paragraph-length response that may also contain equations and/or drawings, explain your reasoning. Neglect any frictional effects due to the table or air resistance.

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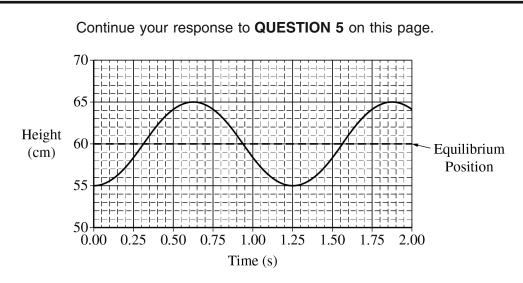
## Begin your response to **QUESTION 5** on this page.



## 5. (7 points, suggested time 13 minutes)

A spring of unknown spring constant  $k_0$  is attached to a ceiling. A lightweight hanger is attached to the lower end of the spring, and a motion detector is placed on the floor facing upward directly under the hanger, as shown in the figure above. The bottom of the hanger is 1.00 m above the motion detector.

A 0.50 kg object is placed on the hanger and allowed to come to rest at the equilibrium position. The spring is then stretched downward a distance  $d_0$  from equilibrium and released at time t = 0. The motion detector records the height of the bottom of the hanger as a function of time. The output from the motion detector is shown in the graph on the following page.



(a) Using the information given and information taken from the graph, calculate the spring constant.

(b) At time 0.75 s, the <u>object-spring-Earth</u> system has a total kinetic energy  $K_0$  and a total potential energy  $U_0$ . At 1.13 s, the object-spring-Earth system again has a total kinetic energy  $K_0$  and a total potential energy  $U_0$ .

i. Explain how a feature of the graph indicates that the total kinetic energy of the system is the same at these two times.

ii. Briefly explain why the total potential energy of the system is the same at these two times.

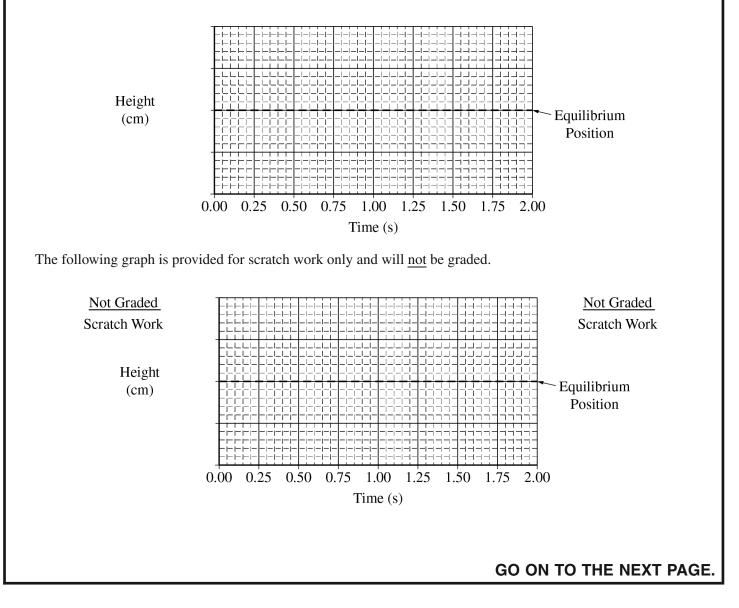
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Continue your response to **QUESTION 5** on this page.

(c) The experiment is repeated with a spring of spring constant  $4k_0$  and that has the same length as the original spring. The 0.50 kg object is hung from the new spring and allowed to come to rest at a new equilibrium position.

i. Determine the new equilibrium position above the motion detector.

ii. The object is again pulled down the same distance  $d_0$  from the equilibrium position and released. On the following graph, draw a curve representing the motion of the object after it is released. Label the vertical axis with an appropriate numerical scale. A grid for scratch (practice) work is also provided.



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2023



# **AP<sup>°</sup> Physics 1: Algebra-Based** Free-Response Questions

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# **AP® PHYSICS 1 TABLE OF INFORMATION**

## CONSTANTS AND CONVERSION FACTORS

Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude,	$e = 1.60 \times 10^{-19} \text{ C}$
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant,	$k = 1/4\pi\varepsilon_0 = 9.0 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2$
Electron mass, $m_e = 9.11 \times 10^{-31} \text{ kg}$	Universal gravitational constant,	$G = 6.67 \times 10^{-11} \text{ m}^3/\text{kg}\cdot\text{s}^2$
Speed of light, $c = 3.00 \times 10^8 \text{ m/s}$	Acceleration due to gravity at Earth's surface,	$g = 9.8 \text{ m/s}^2$

	meter,	m	kelvin,	Κ	watt,	W	degree Celsius,	°C
UNIT	kilogram,	kg	hertz,	Hz	coulomb,	С		
SYMBOLS	second,	S	newton,	Ν	volt,	V		
	ampere,	А	joule,	J	ohm,	Ω		

	PREFIXES								
Factor	Prefix	Symbol							
10 <sup>12</sup>	tera	Т							
10 <sup>9</sup>	giga	G							
$10^{6}$	mega	М							
$10^{3}$	kilo	k							
$10^{-2}$	centi	с							
$10^{-3}$	milli	m							
$10^{-6}$	micro	μ							
10 <sup>-9</sup>	nano	n							
$10^{-12}$	pico	р							

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES									
θ	$0^{\circ}$	$30^{\circ}$	$37^{\circ}$	$45^{\circ}$	$53^{\circ}$	$60^{\circ}$	$90^{\circ}$		
sin <b>θ</b>	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1		
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0		
tanθ	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	∞		

The following conventions are used in this exam.

- I. The frame of reference of any problem is assumed to be inertial unless otherwise stated.
- II. Assume air resistance is negligible unless otherwise stated.
- III. In all situations, positive work is defined as work done <u>on</u> a system.
- IV. The direction of current is conventional current: the direction in which positive charge would drift.
- V. Assume all batteries and meters are ideal unless otherwise stated.

## **MECHANICS**

$$\begin{aligned} v_x &= v_{x0} + a_x t & a = \operatorname{acceleration} \\ A &= \operatorname{amplitude} \\ x &= x_0 + v_{x0}t + \frac{1}{2}a_x t^2 & E = \operatorname{energy} \\ f &= \operatorname{frequency} \\ F &= \operatorname{force} \\ \vec{a} &= \sum \frac{\vec{F}}{m} = \frac{\vec{F}_{met}}{m} & K = \operatorname{kinetic energy} \\ \vec{a} &= \sum \frac{\vec{F}}{m} = \frac{\vec{F}_{met}}{m} & K = \operatorname{spring constant} \\ \vec{F}_f &| \leq \mu |\vec{F}_n| & L = \operatorname{angular momentum} \\ \ell &= \operatorname{length} \\ a_c &= \frac{v^2}{r} & P = \operatorname{power} \\ p &= \operatorname{momentum} \\ \vec{p} &= m\vec{v} & r = \operatorname{radius or separation} \\ \vec{\Delta}\vec{p} &= \vec{F} \Delta t & t = \operatorname{time} \\ \Delta \vec{p} &= \vec{F} \Delta t & t = \operatorname{time} \\ K &= \frac{1}{2}mv^2 & V = \operatorname{volume} \\ v &= \operatorname{speed} \\ \Delta E &= W = F_{\parallel}d = Fd\cos\theta & W = \operatorname{work done on a system} \\ x &= \operatorname{position} \\ P &= \frac{\Delta E}{\Delta t} & q = \operatorname{angular acceleration} \\ \mu &= \operatorname{coefficient of friction} \\ \theta &= \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2 & \theta &= \operatorname{angle} \\ \rho &= \operatorname{density} \\ \omega &= \omega_0 + \alpha t & \tau &= \operatorname{torque} \\ x &= \operatorname{Acos}(2\pi ft) & \alpha &= \operatorname{angular speed} \\ \vec{\alpha} &= \sum \frac{T}{I} &= \frac{\vec{\tau}_{net}}{I} \\ \tau &= r_{\perp}F = rF \sin\theta & T &= \frac{2\pi}{\omega} &= \frac{1}{f} \\ L &= I\omega & T_s &= 2\pi \sqrt{\frac{m}{k}} \\ K &= \frac{1}{2}I\omega^2 & F_s &= 2\pi \sqrt{\frac{k}{g}} \\ |\vec{F}_s| &= k|\vec{x}| & |\vec{F}_g| &= G \frac{m_1m_2}{r^2} \\ U_s &= \frac{1}{2}kx^2 & \vec{g} &= \frac{\vec{F}_g}{m} \\ \rho &= \frac{m}{V} & U_G &= -\frac{Gm_1m_2}{r} \end{aligned}$$

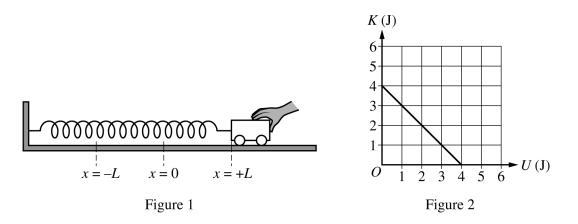
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GEOMETRY AND	FRIGONOMETRY
Rectangle $A = bh$	A = area C = circumference V = volume
Triangle $A = \frac{1}{2}bh$ Circle $A = \pi r^{2}$ $C = 2\pi r$	S = surface area b = base h = height $\ell = \text{length}$ w = width r = radius
Rectangular solid $V = \ell w h$	Right triangle $c^2 = a^2 + b^2$
Cylinder $V = \pi r^{2} \ell$ $S = 2\pi r \ell + 2\pi r^{2}$	$\sin\theta = \frac{a}{c}$ $\cos\theta = \frac{b}{c}$
Sphere $V = \frac{4}{3}\pi r^{3}$ $S = 4\pi r^{2}$	$\tan \theta = \frac{a}{b}$ $c$ $\theta = \frac{1}{90^{\circ}}a$

### Begin your response to **QUESTION 1** on this page.

## PHYSICS 1 SECTION II Time—1 hour and 30 minutes 5 Questions

**Directions:** Questions 1, 4, and 5 are short free-response questions that require about 13 minutes each to answer and are worth 7 points each. Questions 2 and 3 are long free-response questions that require about 25 minutes each to answer and are worth 12 points each. Show your work for each part in the space provided after that part.



<sup>1. (7</sup> points, suggested time 13 minutes)

A cart on a horizontal surface is attached to a spring. The other end of the spring is attached to a wall. The cart is initially held at rest, as shown in Figure 1. When the cart is released, the system consisting of the cart and spring oscillates between the positions x = +L and x = -L. Figure 2 shows the kinetic energy of the cart-spring system as a function of the system's potential energy. Frictional forces are negligible.

(a) On the graph of kinetic energy K versus potential energy U shown in Figure 2, the values for the *x*-intercept and *y*-intercept are the same. Briefly explain why this is true, using physics principles.

Continue your response to **QUESTION 1** on this page.



When the cart is at +L and momentarily at rest, a block is dropped onto the cart, as shown in Figure 3. The block sticks to the cart, and the block-cart-spring system continues to oscillate between -L and +L. The masses of the cart and the block are  $m_0$  and  $3m_0$ , respectively.

(b) The frequency of oscillation before the block is dropped onto the cart is  $f_1$ . The frequency of oscillation after

the block is dropped onto the cart is  $f_2$ . Calculate the numerical value of the ratio  $\frac{f_2}{f_1}$ .

Continue your response to **QUESTION 1** on this page.

(c) The dashed line in Figure 4 shows the kinetic energy K versus potential energy U of the block-cart-spring system after the block is dropped onto the cart. This graph is identical to the graph shown in Figure 2 for the cart-spring system before the block is dropped onto the cart.

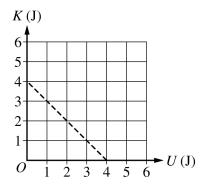
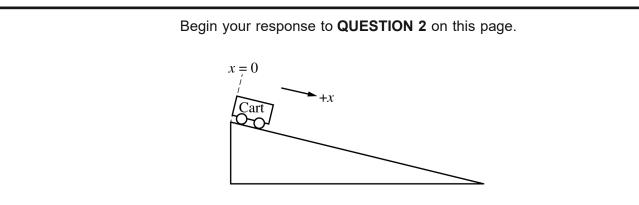


Figure 4

i. Briefly explain why the two graphs must be the same, using physics principles.

ii. After the block is dropped onto the cart, consider a system that consists <u>only</u> of the cart and the spring. On Figure 4, sketch a solid line that shows the kinetic energy of the system that consists of the cart and the spring but not the block after the block is dropped onto the cart.



- 2. (12 points, suggested time 25 minutes)
  - (a) Students conduct an experiment to determine the acceleration a of a cart. The cart is released from rest at the top of the ramp at time t = 0 and moves down the ramp. The x-axis is defined to be parallel to the ramp with its origin at the top, as shown in the figure. The students collect the data shown in the following table.

Position <i>x</i> (m)	Time t (s)	
0.06	0.39	
0.14	0.59	
0.24	0.77	
0.37	0.96	
0.55	1.20	

i. Indicate which quantities could be graphed to yield a straight line whose slope could be used to determine the acceleration *a* of the cart. You may use the remaining columns in the table, as needed, to record any quantities (including units) that are not already in the table.

Vertical axis: \_\_\_\_\_ Horizontal axis: \_\_\_\_\_

### Continue your response to **QUESTION 2** on this page.

ii. On the following grid, plot the appropriate quantities to create a graph that can be used to determine the acceleration a of the cart as it rolls down the ramp. Clearly scale and label all axes (including units), as appropriate. Draw a straight line that best represents the data.

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iii. Using the line you drew in part (a)(ii), calculate an experimental value for the acceleration a of the cart as it rolls down the ramp.

(b) The students are asked to determine an experimental value for the acceleration due to gravity  $g_{exp}$  using their data.

i. What additional quantities do the students need to measure in order to calculate  $g_{exp}$  from a ?

ii. Write an expression for the value of  $g_{exp}$  in terms of *a*.

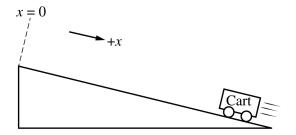
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Continue your response to **QUESTION 2** on this page.

(c) The students calculate the value of  $g_{exp}$  to be significantly lower than the accepted value of 9.8 m/s<sup>2</sup>.

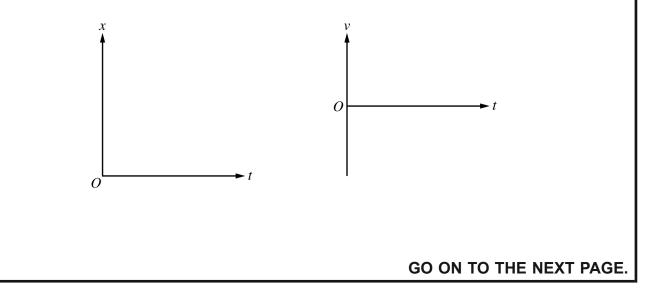
i. What is a physical reason, other than friction or air resistance, that could lead to a significant difference in the experimentally determined value of  $g_{exp}$ ?

ii. Briefly explain how the physical reason you identified in part (c)(i) would lead to the decrease in the experimentally determined value of  $g_{exp}$ .



The students want to confirm that the acceleration is the same whether the cart rolls up or down the ramp. The students start the cart at the bottom and give the cart a quick push so that it rolls up the ramp and momentarily comes to rest. The *x*-axis is still defined to be parallel to the ramp with the origin at the top.

(d) On the following graphs, sketch the position x and velocity v as functions of time t that correspond to the scenario shown while the cart moves up the ramp.

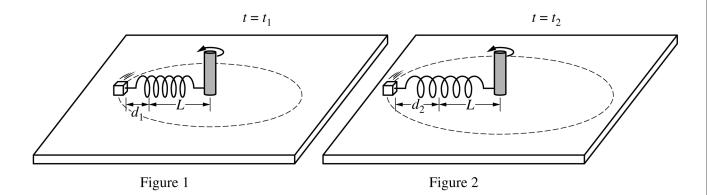


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Begin your response to QUESTION 3 on this page.

3. (12 points, suggested time 25 minutes)

A small block of mass  $m_0$  is attached to the end of a spring of spring constant  $k_0$  that is attached to a rod on a horizontal table. The rod is attached to a motor so that the rod can rotate at various speeds about its axis. When the rod is not rotating, the block is at rest and the spring is at its unstretched length L, as shown. All frictional forces are negligible.

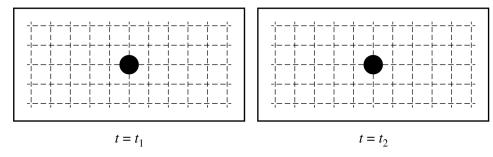


(a) At time  $t = t_1$ , the rod is spinning such that the block moves in a circular path with a constant tangential speed  $v_1$  and the spring is stretched a distance  $d_1$  from the spring's unstretched length, as shown in Figure 1. At time  $t = t_2$ , the rod is spinning such that the block moves in a circular path with a constant tangential speed  $v_2$  and the spring is stretched a distance  $d_2$  from the spring's unstretched length, where  $d_2 > d_1$ , as shown in Figure 2.

Continue your response to QUESTION 3 on this page.

i. On the following dots, which represent the block at the locations shown in Figure 1 and Figure 2, draw the force that is exerted on the block by the spring at times  $t = t_1$  and  $t = t_2$ . The spring force must be represented by a distinct arrow starting on, and pointing away from, the dot.

<u>Note:</u> Draw the relative lengths of the vectors to reflect the relative magnitudes of the forces exerted by the spring at both times.



ii. Referencing  $d_1$  and  $d_2$ , describe your reasoning for drawing the arrows the length that you did in part (a)(i).

iii. Is the tangential speed  $v_1$  of the block at time  $t = t_1$  greater than, less than, or equal to the tangential speed  $v_2$  of the block at time  $t = t_2$ ?

 $v_1 > v_2$   $v_1 < v_2$   $v_1 = v_2$ 

Justify your answer without using equations.

Continue your response to **QUESTION 3** on this page.

(b) Consider a scenario where the block travels in a circular path where the spring is stretched a distance d from its unstretched length L.

i. Determine an expression for the magnitude of the net force  $F_{net}$  exerted on the block. Express your answer in terms of  $m_0$ ,  $k_0$ , L, d, and fundamental constants, as appropriate.

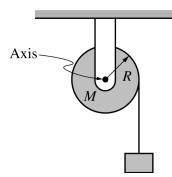
ii. Derive an equation for the tangential speed v of the block. Express your answer in terms of  $m_0$ ,  $k_0$ , L, d, and fundamental constants, as appropriate.

(c) Does your equation for the tangential speed v of the block from part (b)(ii) agree with your reasoning from part (a) ?

Yes No

Explain your reasoning.

### Begin your response to **QUESTION 4** on this page.

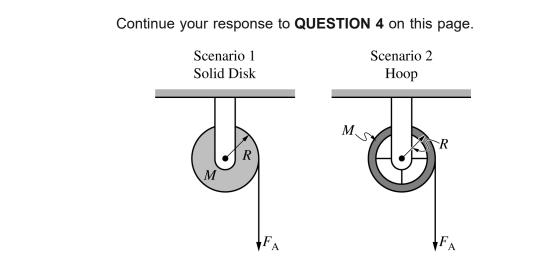


4. (7 points, suggested time 13 minutes)

A block of unknown mass is attached to a long, lightweight string that is wrapped several turns around a pulley mounted on a horizontal axis through its center, as shown. The pulley is a uniform solid disk of mass M and radius R. The rotational inertia of the pulley is described by the equation  $I = \frac{1}{2}MR^2$ . The pulley can rotate about its center with negligible friction. The string does not slip on the pulley as the block falls.

When the block is released from rest and as the block travels toward the ground, the magnitude of the tension exerted on the block by the string is  $F_{T}$ .

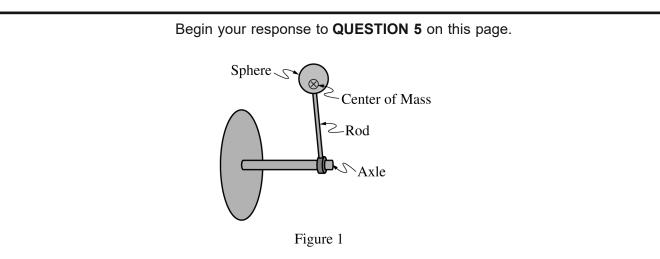
(a) Determine an expression for the magnitude of the angular acceleration  $\alpha_D$  of the disk as the block travels downward. Express your answer in terms of M, R,  $F_T$ , and physical constants as appropriate.



Scenarios 1 and 2 show two different pulleys. In Scenario 1, the pulley is the same solid disk referenced in part (a). In Scenario 2, the pulley is a hoop that has the same mass M and radius R as the disk. Each pulley has a lightweight string wrapped around it several turns and is mounted on a horizontal axle, as shown. Each pulley is free to rotate about its center with negligible friction.

In both scenarios, the pulleys begin at rest. Then both strings are pulled with the same constant force  $F_A$  for the same time interval  $\Delta t$ , causing the pulleys to rotate without the string slipping. After time interval  $\Delta t$ , the change in angular momentum of the disk is equal to the change in angular momentum of the hoop, but the change in rotational kinetic energy for the disk is greater than that of the hoop.

(b) Consider scenarios 1 and 2 at the end of time interval  $\Delta t$ . In a clear, coherent paragraph-length response that may also contain equations and drawings, explain why the change in angular momentum of both pulleys is the same but the change in rotational kinetic energy is greater for the disk.



5. (7 points, suggested time 13 minutes)

A rod with a sphere attached to the end is connected to a horizontal mounted axle and carefully balanced so that it rests in a position vertically upward from the axle. The center of mass of the rod-sphere system is indicated with a  $\otimes$ , as shown in Figure 1. The sphere is lightly tapped, and the rod-sphere system rotates clockwise with negligible friction about the axle due to the gravitational force.

A student takes a video of the rod rotating from the vertically upward position to the vertically downward position. Figure 2 shows five frames (still shots) that the student selected from the video. Note: these frames are <u>not</u> equally spaced apart in time.

Axle			(O) (I) (I) (I) (I) (I) (I) (I) (I) (I) (I	8
Frame A	Frame B	Frame C	Frame D	Frame E

Figure 2

GO ON TO THE NEXT PAGE.

Continue your response to **QUESTION 5** on this page.

(a) Use the frames of the video shown in Figure 2 to answer the following questions.

i. In which frame is the angular acceleration of the rod-sphere system the greatest? Justify your answer.

ii. In which frame is the rotational kinetic energy of the rod-sphere system the greatest? Briefly justify your answer.

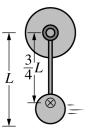


Figure 3

(b) The rod-sphere system has mass M and length L, and the center of mass is located a distance  $\frac{3}{4}L$  from the

axle, shown in Figure 3.

i. Derive an expression for the change in kinetic energy of the <u>rod-sphere-Earth</u> system from the moment shown in Frame A to the moment shown in Frame E. Express your answer in terms of M, L, and fundamental constants, as appropriate.

ii. Briefly explain why the rod and sphere gain kinetic energy, even if Earth is not included in the system.

## GO ON TO THE NEXT PAGE.

STOP

END OF EXAM

2024



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	meter,	m	kelvin,	Κ	watt,	W	degree Celsius,	°C
UNIT	kilogram,	kg	hertz,	Hz	coulomb,	С		
SYMBOLS	second,	S	newton,	Ν	volt,	V		
	ampere,	А	joule,	J	ohm,	Ω		

	PREFIXES								
Factor	Prefix	Symbol							
10 <sup>12</sup>	tera	Т							
10 <sup>9</sup>	giga	G							
$10^{6}$	mega	М							
$10^{3}$	kilo	k							
$10^{-2}$	centi	с							
$10^{-3}$	milli	m							
$10^{-6}$	micro	μ							
10 <sup>-9</sup>	nano	n							
10 <sup>-12</sup>	pico	р							

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES									
$0^{\circ}$	$30^{\circ}$	$37^{\circ}$	$45^{\circ}$	$53^{\circ}$	$60^{\circ}$	$90^{\circ}$			
0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1			
1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0			
0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	∞			
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- IV. The direction of current is conventional current: the direction in which positive charge would drift.
- V. Assume all batteries and meters are ideal unless otherwise stated.

## **AP<sup>®</sup> PHYSICS 1 EQUATIONS**

MECHANICS		GEOMETRY AND TRIGONOMETRY		
$v_x = v_{x0} + a_x t$	a = acceleration A = amplitude	Rectangle $A = bh$	A = area C = circumference	
$x = x_0 + v_{x0}t + \frac{1}{2}a_xt^2$	d = distance E = energy	Triangle	V = volume S = surface area	
$v_x^2 = v_{x0}^2 + 2a_x(x - x_0)$	f = frequency F = force	$A = \frac{1}{2}bh$	b = base h = height	
$\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$	I = rotational inertia K = kinetic energy k = spring constant	Circle $A = \pi r^2$	$\ell$ = length w = width r = radius	
$\left \vec{F}_{f}\right  \leq \mu \left \vec{F}_{n}\right $	L = angular momentum $\ell = $ length	$C = 2\pi r$		
$a_c = \frac{v^2}{r}$	m = mass P = power p = momentum	Rectangular solid $V = \ell w h$	Right triangle $c^2 = a^2 + b^2$	
$\vec{p} = m\vec{v}$	r = radius or separation	Cylinder	$\sin\theta = \frac{a}{c}$	
$\Delta \vec{p} = \vec{F}  \Delta t$	T = period t = time	$V = \pi r^2 \ell$ $S = 2\pi r \ell + 2\pi r^2$	$\cos\theta = \frac{b}{c}$	
$K = \frac{1}{2}mv^2$	U = potential energy V = volume v = speed	Sphere	$\tan \theta = \frac{a}{b}$	
$\Delta E = W = F_{\parallel}d = Fd\cos\theta$	W = work done on a system x = position	$V = \frac{4}{3}\pi r^3$ $S = 4\pi r^2$	$e^{c}$ $a$ $g_{0}^{\circ}$	
$P = \frac{\Delta E}{\Delta t}$	y = height $\alpha =$ angular acceleration $\mu =$ coefficient of friction	$S = 4\pi r$	$\frac{10}{b}$	
$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$	$\theta$ = angle $\rho$ = density			
$\omega = \omega_0 + \alpha t$	$\tau$ = torque			
$x = A\cos(2\pi ft)$	$\omega$ = angular speed			
$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$	$\Delta U_g = mg \Delta y$			
$\tau = r_{\perp}F = rF\sin\theta$	$T = \frac{2\pi}{\omega} = \frac{1}{f}$			
$L = I\omega$ $\Delta L = \tau \Delta t$	$T_s = 2\pi \sqrt{\frac{m}{k}}$			
$K = \frac{1}{2}I\omega^2$	$T_p = 2\pi \sqrt{\frac{\ell}{g}}$			
$\left \vec{F}_{s}\right  = k \left \vec{x}\right $	$\left \vec{F}_g\right  = G \frac{m_1 m_2}{r^2}$			
$U_s = \frac{1}{2}kx^2$	$\vec{g} = \frac{\vec{F}_g}{m}$			
$\rho = \frac{m}{V}$	$U_G = -\frac{Gm_1m_2}{r}$			

### Begin your response to **QUESTION 1** on this page.

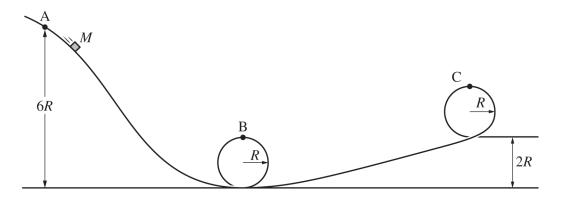
## PHYSICS 1

## **SECTION II**

### Time—1 hour and 30 minutes

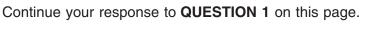
#### **5** Questions

**Directions:** Questions 1, 4, and 5 are short free-response questions that require about 13 minutes each to answer and are worth 7 points each. Questions 2 and 3 are long free-response questions that require about 25 minutes each to answer and are worth 12 points each. Show your work for each part in the space provided after that part.



1. (7 points, suggested time 13 minutes)

A block of mass M is released from rest at Point A, a height 6R above the horizontal. After being released, the block slides down a track, as shown. When released from Point A, the block does not lose contact with the track at any point. Points B and C are located at the highest points of their respective circular loops, both of radius R. All frictional forces are negligible.



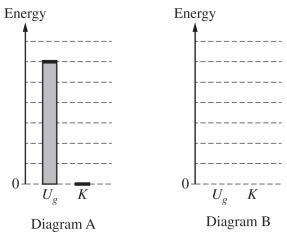


Diagram A shows an energy bar chart that represents the gravitational potential energy  $U_g$  of the block-Earth system and the kinetic energy K of the block at Point A, when the block is released from rest at height 6R.

- (a) **Draw** shaded regions in Diagram B that represent the gravitational potential energy  $U_g$  and kinetic energy K of the block-Earth system when the block is located at Point B, a height 2R above the horizontal.
  - Shaded regions should start at the dashed line that represents zero energy.
  - Represent any energy that is equal to zero with a distinct line on the zero-energy line.
  - The relative height of each shaded region should reflect the magnitude of the respective energy consistent with the scale shown in Diagram A.
- (b) Starting with conservation of energy, **derive** an expression for the speed of the block at Point B. Express your answer in terms of R and physical constants, as appropriate. Begin your derivation by writing a fundamental physics principle or an equation from the reference book.

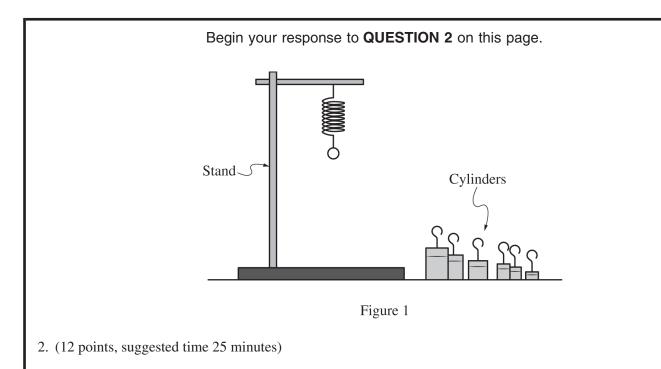
### Continue your response to **QUESTION 1** on this page.

(c)

i. On the following dot that represents the block, **draw** and **label** the forces (not components) that are exerted on the block at the instant the block slides through Point C. Each force must be represented by a distinct arrow starting on, and pointing away from, the dot.



ii. A student claims that 4R is the minimum height of Point A, such that the block can slide through Point C without losing contact with the track after the block is released from rest. Briefly **explain** why this claim is incorrect.



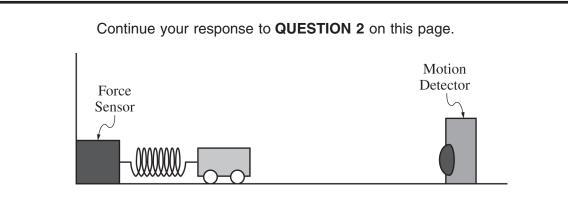
A student hangs a spring of unknown spring constant k vertically by attaching one end to a stand, as shown in Figure 1. The other end of the spring has a small loop from which small cylinders can be hung. In addition to the spring, the student has access <u>only</u> to a variety of cylinders of unknown masses, a stopwatch, and a digital scale.

(a) Design an experimental procedure the student could use to determine the spring constant k of the spring.

In the following table, list the quantities that would be measured using only the provided equipment in your experiment. Define a symbol to represent each quantity.

In the space below the table, **describe** the overall procedure. Provide enough detail so that another student could replicate the experiment, including any steps necessary to reduce experimental uncertainty. As needed, use the symbols defined in the table. If needed, you may include a simple diagram of the setup with your procedure.

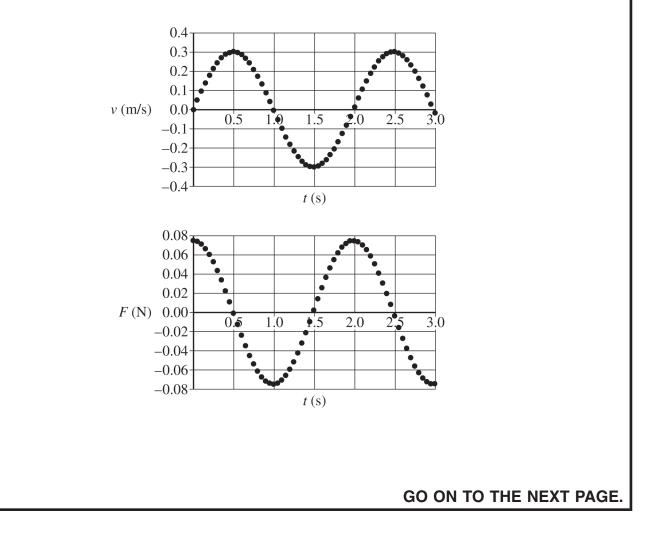
Quantity to Be Measured	Symbol for Quantity	Equipment for Measurement	
		Stopwatch	
		Digital scale	
Procedure (and diagram, if ne	eded)		
i Indianta the quantities the	t aculd he plotted to	meduar a linear more whose slone can be up	and to
1. <b>Indicate</b> the quantities that		produce a linear graph whose slope can be us	sed to
determine the spring constant			
		ontal axis:	
determine the spring constant Vertical axis: ii. Briefly <b>describe</b> how the	Horiz	ontal axis:outline the spring con	stant k
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determine the spring constant Vertical axis: ii. Briefly <b>describe</b> how the	Horiz		stant k





In a different experiment, the student attaches one end of a spring to a force sensor that is attached to a wall. The other end of the spring is attached to a cart with mass m = 0.25 kg. The student places a motion detector to the right of the cart, as shown in Figure 2, and pulls the cart to the right a small distance so that the spring is stretched. The student releases the cart from rest, and the cart-spring system oscillates.

The following graphs show the velocity v of the cart and the force F exerted on the cart by the spring as functions of time t.



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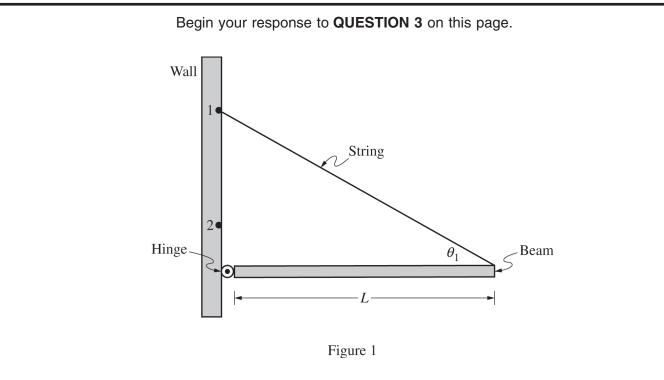
Continue your response to QUESTION 2 on this page.

(c)

i. Using the data in the <u>velocity-time graph</u>, **calculate** the change in kinetic energy of the cart from t = 0.5 s to t = 2.0 s. Show your steps and substitutions.

ii. Using the data in the <u>force-time graph</u>, **estimate** the change in momentum of the cart from t = 0.5 s to t = 2.5 s. Briefly **explain** how you arrived at your estimation.

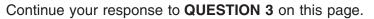
iii. Do the data from the velocity-time graph confirm your estimation from part (c)(ii) ? Briefly explain.

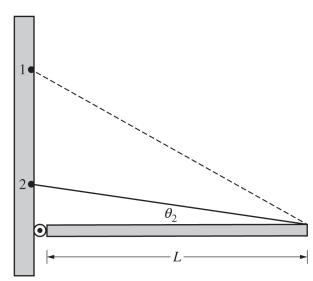


3. (12 points, suggested time 25 minutes)

The left end of a uniform beam of mass M and length L is attached to a wall by a hinge, as shown in Figure 1. One end of a string with negligible mass is attached to the right end of the beam. The other end of the string is attached to the wall above the hinge at Point 1. The beam remains horizontal. The hinge exerts a force on the beam of magnitude  $F_{\rm H}$ , and the angle between the beam and the string is  $\theta = \theta_1$ .

(a) The following rectangle represents the beam in Figure 1. On the rectangle, **draw** and **label** the forces (not components) exerted on the beam. Draw each force as a distinct arrow starting on, and pointing away from, the point at which the force is exerted.





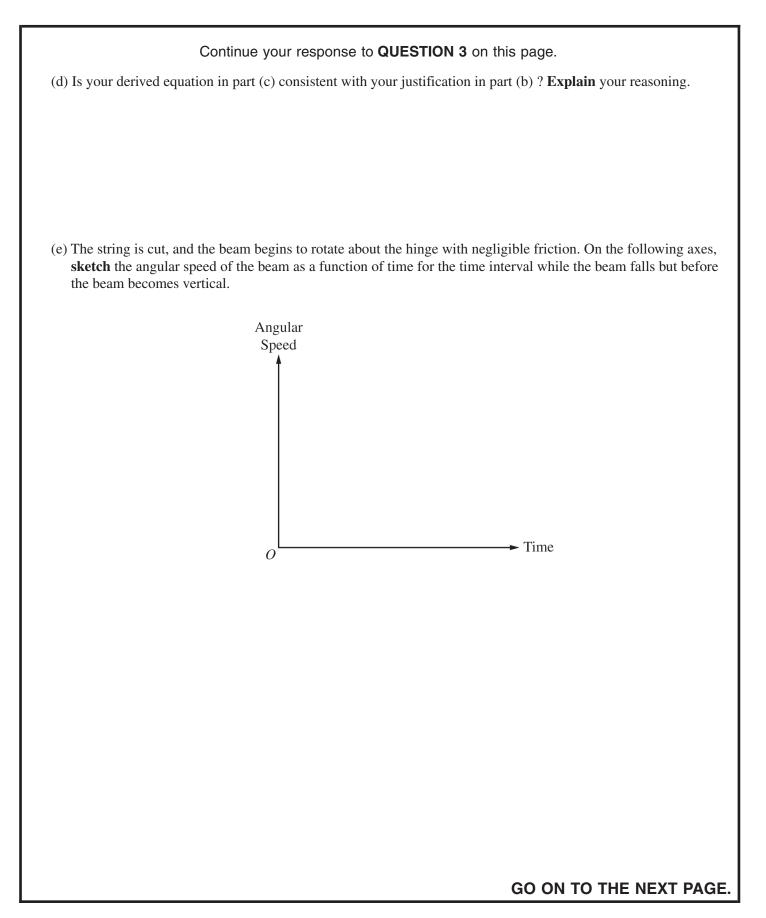


(b) The string is then attached lower on the wall, at Point 2, and the beam remains horizontal, as shown in Figure 2. The angle between the beam and the string is  $\theta = \theta_2$ . The dashed line represents the string shown in Figure 1.

The magnitude of the tension in the string shown in Figure 1 is  $F_{T1}$ . The magnitude of the tension in the string shown in Figure 2 is  $F_{T2}$ . **Indicate** which of the following correctly compares  $F_{T2}$  with  $F_{T1}$ .

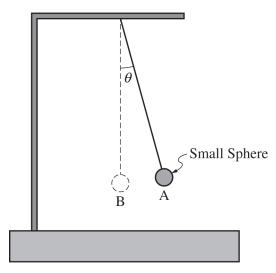
Briefly **justify** your answer, using qualitative reasoning beyond referencing equations.

(c) Starting with Newton's second law in rotational form, **derive** an expression for the magnitude of the tension in the string. Express your answer in terms of M,  $\theta$ , and physical constants, as appropriate. Begin your derivation by writing a fundamental physics principle or an equation from the reference book.



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Begin your response to **QUESTION 4** on this page.



4. (7 points, suggested time 13 minutes)

A simple pendulum consists of a small sphere that hangs from a string with negligible mass. The top end of the string is fixed. The sphere is pulled to Point A so that the string makes a small angle  $\theta$  with the vertical, as shown. The sphere is then released from rest and swings through its lowest point at Point B. The work done on the sphere by Earth between points A and B is  $W_{\rm E}$ .

The pendulum is then taken to Planet X. The mass of Planet X is the same as the mass of Earth, but the radius of Planet X is greater than the radius of Earth. The sphere is again brought to Point A (displaced  $\theta$  from the vertical), released from rest, and swings through its lowest point at Point B. The work done on the sphere by Planet X between points A and B is  $W_X$ .

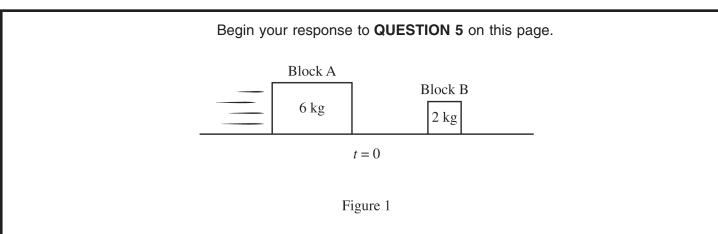
(a) **Justify** why  $W_X$  is less than  $W_E$ .

## Continue your response to QUESTION 4 on this page.

A new pendulum is made by hanging the same small sphere from a different string with negligible mass. The new string is slightly elastic, and the length of the string may increase or decrease depending on the tension applied to the string. On Earth, when the sphere is again displaced  $\theta$  from the vertical and released from rest, the new pendulum oscillates with period  $T_{\rm E}$ .

The new pendulum is then taken to a different planet, Planet Y. The radius of Planet Y is the same as the radius of Earth, but the mass of Planet Y is larger than the mass of Earth. On Planet Y, when the sphere is again displaced from the vertical and released from rest, the new pendulum oscillates with period  $T_{\rm Y}$ .

(b) In a clear, coherent paragraph-length response that may also contain drawings, **explain** how  $T_{\rm Y}$  <u>could be larger</u> than  $T_{\rm E}$  but also <u>could be smaller</u> than  $T_{\rm E}$ .



5. (7 points, suggested time 13 minutes)

At time t = 0, Block A slides along a horizontal surface toward Block B, which is initially at rest, as shown in Figure 1. The masses of blocks A and B are 6 kg and 2 kg, respectively. The blocks collide <u>elastically</u> at t = 1.0 s, and as a result, the magnitude of the change in kinetic energy of Block B is 9 J. All frictional forces are negligible.

(a) **Determine** the speed of Block B immediately after the collision.

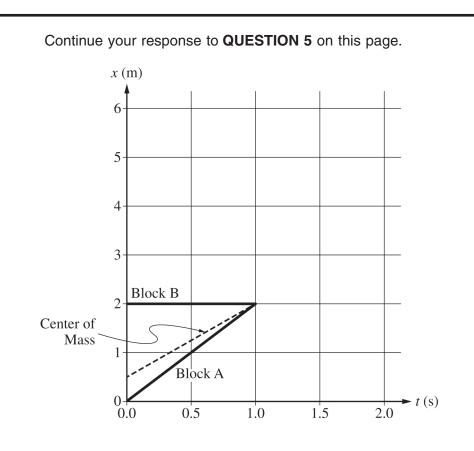


Figure 2

The graph shown in Figure 2 represents the positions x of Block A, Block B, and the center of mass of the two-block system as functions of t between t = 0 and t = 1.0 s.

- (b) On the graph in Figure 2, draw and label three lines to represent the positions of Block A, Block B, and the center of mass of the two-block system as functions of t between t = 1.0 s and t = 2.0 s. Each line should be distinctly labeled.
- (c) Consider if in the original scenario, instead of colliding elastically, the blocks collided and stuck together. Describe how the line drawn for the center of mass in part (b) would change, if at all. Briefly justify your response.

STOP

END OF EXAM